

UNCLASSIFIED

AD NUMBER

ADB015244

LIMITATION CHANGES

TO:

Approved for public release; distribution is unlimited.

FROM:

Distribution authorized to U.S. Gov't. agencies only; Test and Evaluation; 24 MAY 1976. Other requests shall be referred to Naval Weapons Center, China Lake, CA 93555.

AUTHORITY

USNWC notice, 5 Oct 1978

THIS PAGE IS UNCLASSIFIED

RIA-76-U634

RD-B 015244

USADACS Technical Library



5 0712 01004620 8

TECHNICAL LIBRARY

Parametric Trajectory Program

by

John E. Peterson

Aircraft Armament Division

Systems Development Department

OCTOBER 1976

Distribution limited to U.S. Government agencies only; test and evaluation; 24 May 1976. Other requests for this document must be referred to the Naval Weapons Center.

Naval Weapons Center

CHINA LAKE, CALIFORNIA 93555



Naval Weapons Center

AN ACTIVITY OF THE NAVAL MATERIAL COMMAND

R. G. Freeman, III, RAdm., USN Commander
G. L. Hollingsworth Technical Director

FOREWORD

The documentation of the computer program described in this report was performed during Fiscal Year 1976 and is a subproject supported by Naval Air Systems Command AirTask A350-350B/008B/4F32-353-505.

It is part of a continuing effort to describe and document methodologies for computer simulation of aeroballistic performance of small-caliber, gun-fired projectiles.

This report was reviewed for technical accuracy by Richard Compton.

Released by
M. M. ROGERS, Head
Systems Development Department
24 May 1976

Under authority of
G. L. HOLLINGSWORTH
Technical Director

NWC Technical Publication 5864

Published by Technical Information Department
Manuscript 5362/MS 76-76
Collation Cover, 38 leaves
First printing 55 unnumbered copies

THIS REPORT HAS BEEN DELIMITED
AND CLEARED FOR PUBLIC RELEASE
UNDER DOD DIRECTIVE 5200.2D AND
NO RESTRICTIONS ARE IMPOSED UPON
ITS USE AND DISCLOSURE.

DISTRIBUTION STATEMENT A

APPROVED FOR PUBLIC RELEASE;
DISTRIBUTION UNLIMITED.

UNCLASSIFIED

SECURITY CLASSIFICATION OF THIS PAGE (When Data Entered)

REPORT DOCUMENTATION PAGE		READ INSTRUCTIONS BEFORE COMPLETING FORM
1. REPORT NUMBER NWC TP 5864	2. GOVT ACCESSION NO.	3. RECIPIENT'S CATALOG NUMBER
4. TITLE (and Subtitle) Parametric Trajectory Program		5. TYPE OF REPORT & PERIOD COVERED Computer Program FY 1976
		6. PERFORMING ORG. REPORT NUMBER
7. AUTHOR(s) John E. Peterson	8. CONTRACT OR GRANT NUMBER(s)	
9. PERFORMING ORGANIZATION NAME AND ADDRESS Naval Weapons Center China Lake, CA 93555		10. PROGRAM ELEMENT, PROJECT, TASK AREA & WORK UNIT NUMBERS AirTask A350-350B/008B/ 4F32-353-505
11. CONTROLLING OFFICE NAME AND ADDRESS		12. REPORT DATE October 1976
		13. NUMBER OF PAGES 74
14. MONITORING AGENCY NAME & ADDRESS (if different from Controlling Office)		15. SECURITY CLASS. (of this report) UNCLASSIFIED
		15a. DECLASSIFICATION/DOWNGRADING SCHEDULE
16. DISTRIBUTION STATEMENT (of this Report) Distribution limited to U.S. Government agencies only; test and evaluation; 24 May 1976. Other requests for this document must be referred to the Naval Weapons Center.		
17. DISTRIBUTION STATEMENT (of the abstract entered in Block 20, if different from Report)		
18. SUPPLEMENTARY NOTES		
19. KEY WORDS (Continue on reverse side if necessary and identify by block number) Guns Ballistics Trajectories Trajectory Table Computer Programs		
20. ABSTRACT (Continue on reverse side if necessary and identify by block number) See back of form.		

UNCLASSIFIED

SECURITY CLASSIFICATION OF THIS PAGE(When Data Entered)

(U) *Parametric Trajectory Program*, by John E. Peterson. China Lake, Calif., Naval Weapons Center, October 1976. 74 pp. (NWC TP 5864, publication UNCLASSIFIED.)

(U) This aeroballistic three-degree-of-freedom computer program was developed to predict trajectories of both air-fired and ground-fired projectiles, and to prepare trajectory tables to assist designers of new or experimental ordnance.

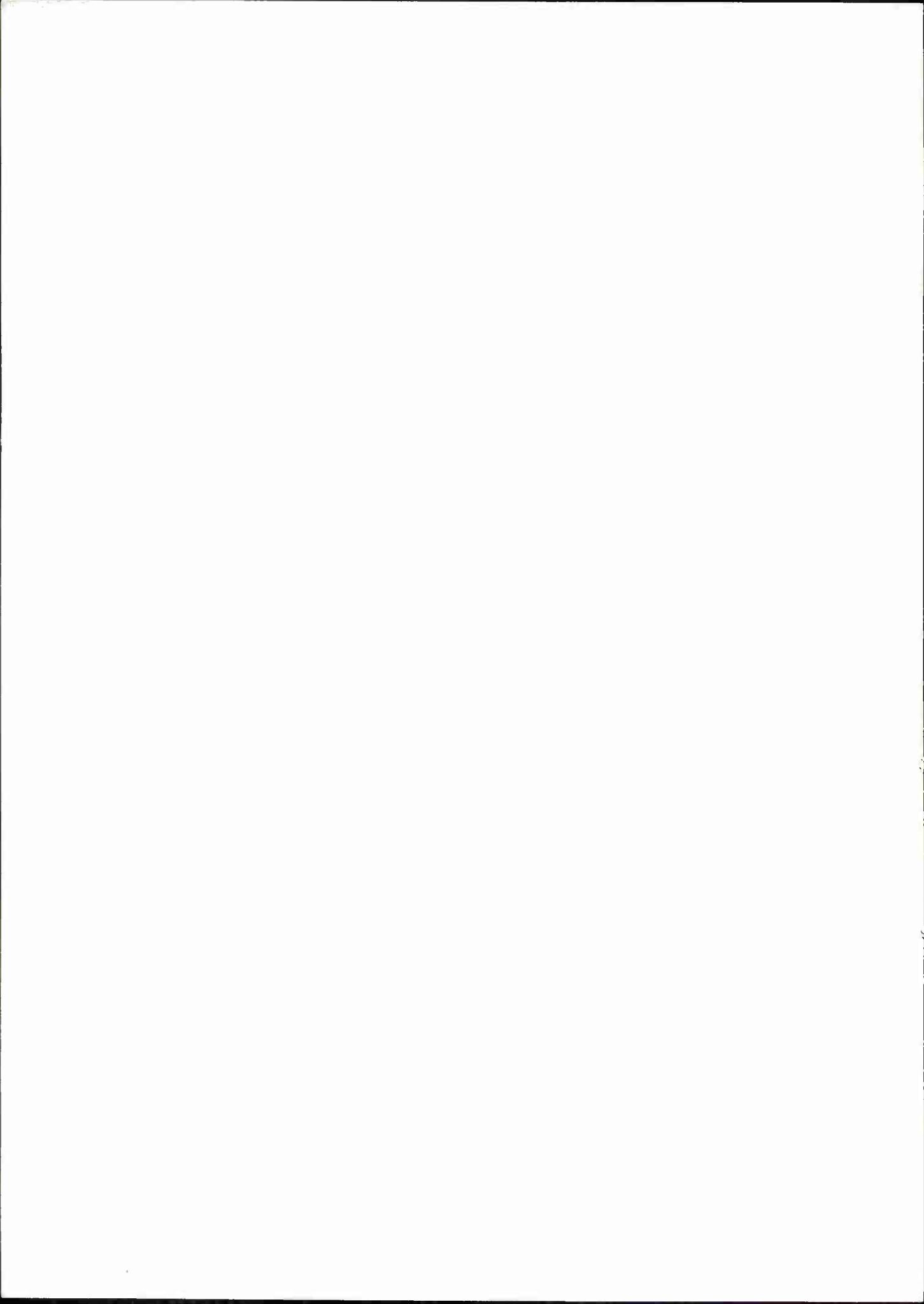
(U) It is an efficient and inexpensive program to run, and is thus valuable in preparing extensive data for analysis of the various projectile design parameters.

UNCLASSIFIED

SECURITY CLASSIFICATION OF THIS PAGE(When Data Entered)

CONTENTS

Introduction	3
Program Description	4
Aeroballistic Equations	4
Standard Atmosphere	7
Input Data	7
Card Output	10
Typical Trajectory Table Output	11
Bibliography	13
Appendixes:	
A. Program Glossary	15
B. Program Listing	19
C. Program References to Variables	30
D. Program Flow Chart	33
E. Typical Trajectory Table Output	51
F. Typical Trajectory Table Input	71



INTRODUCTION

This report describes a three-degree-of-freedom particle trajectory program for calculation of range tables and trajectories for gun-fired projectiles. It has been designed to give maximum data coverage needed by the projectile designers and weapon effectiveness analysts, consistent with minimum computer time and cost. This permits large numbers of computer runs, at minimal cost, for parametric studies involving a number of design parameters, and for design optimization.

While this program was designed for the UNIVAC 1110 computer, it is written in standard FORTRAN IV, and is easily adapted for other computers using this language. The program is also designed for easy modification and, in actual practice, a large number of variations have been used for special requirements and conditions, such as the tail-chase and head-on firings, special atmospheric models, special input format, etc.

The accuracy of this program has been verified with "real life" data obtained from instrumented range firings, with the computed trajectory data agreeing within the experimental error of the instrumentation. However, in common with all three-degree-of-freedom programs, it does not give dynamic stability data. When this is needed, the six-degree-of-freedom programs must be used.

The primary feature of this program is to prepare trajectory tables in final form, ready for use as "masters" in reports and other publications. These tables include a total of 14 variables, as follows: time, altitude, velocity, horizontal range, slant range, trajectory drop, static moment coefficient per radian, drag, kinetic (impact) energy, yaw of repose, Mach number, spin, impact angle, and the gyroscopic stability factor.

The second feature of this program is the card output for use in various plotting programs. These card outputs permit complete flexibility in displaying a series of selected runs in parametric plots. While special plotting programs have been prepared for these card outputs, they are written for use with the DISSPLA plotting system, and will be described in a separate report.

PROGRAM DESCRIPTION

This three-degree-of-freedom point trajectory program was designed for use in preparing trajectory data for air-to-air, air-to-surface (strafing), or surface-to-surface firing conditions. It is written in standard FORTRAN IV and designed for use with the UNIVAC 1110 computer, but it should be usable with any computer using standard FORTRAN IV or V language. To reduce computer time and cost, subroutines were not used, and this makes the program very inexpensive to run.

The program consists of 283 cards for the basic program and 19 cards for the data deck. The program glossary is shown in Appendix A, and the program is listed in Appendix B. The input deck is described separately in this report.

Several versions of this basic program have been prepared and used by the author for special requirements, such as unusual atmospheric models, head-on and tail-chase firing conditions, etc. To aid the reader in preparing such special programs, a complete listing of the program line number references is shown in Appendix C, and a complete flow chart of the program is shown in Appendix D. Sample outputs and inputs are included in Appendixes E and F.

AEROBALLISTIC EQUATIONS

The basic equations for this parametric trajectory program are given below.

Drag Equations

$$D = (1/2) \rho V^2 S C_D$$

where

D = drag, lb

ρ = air density, slugs/ft³

V = velocity, ft/s

S = frontal area, ft²

C_D = drag coefficient

and

$$C_D = C_{D_0} + C_{D_0} (\delta_r)^2$$

where

C_D = drag coefficient

C_{D_0} = drag coefficient at zero yaw

δ_r = yaw of repose, rad

Note: For this program, the angle of attack and yaw of repose are considered equivalent.

Gyroscopic Stability Factor Equation

$$s_g = \frac{2(I_x)^2 p^2}{\pi \rho I_y d^3 v^2 C_{M_\alpha}}$$

where

s_g = gyroscopic stability factor

I_x = axial moment of inertia, slug-ft²

I_y = transverse moment of inertia, slug-ft²

p = roll rate, rad/s

d = diameter, ft

v = velocity, ft/s

C_{M_α} = static moment coefficient, per rad

Yaw of Repose Equation

$$\delta_r = \frac{I_x g p \cos \theta}{(\rho/2) S d C_{M_\alpha} v^3}$$

where

δ_r = yaw of repose, rad
 I_x = axial moment of inertia, slug-ft²
 g = gravitational constant, ft/s²
 p = roll rate, rad/s
 θ = trajectory angle, rad
 ρ = air density, slug/ft³
 S = frontal area, ft²
 d = diameter, ft
 $C_{M\alpha}$ = static moment coefficient, per rad
 V = velocity, ft/s

Trajectory Increments

$$\bar{V} = V_o + (A_o + A_t/4) \Delta t$$

$$\bar{\theta} = \theta_o - \cos \theta \Delta t / \bar{V}$$

$$A_t = -(g \sin \theta + D/m)$$

$$\Delta z = (\bar{V} \sin \theta) \Delta t$$

where

A = acceleration, ft/s²
 D = drag, lb
 m = mass, slugs
 V = velocity, ft/s
 θ = trajectory angle
 x = horizontal distance, ft
 z = vertical distance, ft
 g = gravitational constant, ft/s²

STANDARD ATMOSPHERE

This program uses the ICAO standard atmosphere. A sea level pressure of 760 mm of mercury at a temperature of 15°C is assumed. This is equivalent to 14.69 psi and 59°F. The standard density of dry air at these standard conditions is 0.002378 slug/ft³ (NACA 1942). The temperature variation with altitude is as follows:

Up to 36,500 ft

$$T = 59 - 0.00356 h$$

where

T = temperature, °F

h = altitude (ft) above mean sea level (MSL)

Above 36,500 ft

Temperature is assumed to be a constant -70°F.

The acoustic velocity is given by the following equation:

$$V_a = 49.1 \sqrt{460 + T}$$

where

V_a = acoustic velocity, ft/s

T = temperature, °F

INPUT DATA

The data input for this program is in the form of a 19-card input data deck for a normal individual computer run, as shown in Table 1. However, as noted in the table, additional runs are possible.

The program uses a 12-point "drag table," including both 12 points for the drag coefficient at zero yaw, and 12 points for the static moment coefficient, per rad. The program then interpolates the data as required between these points. For Mach numbers above or below the range of these data, the program uses a constant maximum or minimum value, i.e., the last data point. While it is possible to modify the program to accept fewer than 12 data points, experience has shown that at least this number should be used.

It is possible to make additional runs using the same general projectile configuration, but changing the firing conditions and/or the projectile weight, moments of inertia, or muzzle velocity. In this case, as shown in Table 1, cards 16-19 must be repeated.

TABLE 1. Input Data.

Symbol	Format	Description Cards 1-12	Units
N	I2,8X	Drag table line number	
CDO(I,1)	F10.4	Mach number for CDO(I,2)	
CDO(I,2)	F10.4	Drag coefficient at zero yaw	
CMA(I,1)	F10.4	Mach number for CMA(I,2)	
CMA(I,2)	F10.4	Static moment coefficient, per rad	
Card 13			
KEA	8X,I2	Rifling exit angle	degrees (portion)
KEB	8X,I2	Rifling exit angle	minutes (portion)
CG	F10.3	Center of gravity, from base	inches
Card 14			
FFD	F10.5	Drag table scaling constant	(Note 1)
FFM	F10.5	Scaling constant	(Note 1)
CDD2	F10.5	Yaw-drag coefficient, per rad ²	
TWIST	F10.5	Rifling twist	calibers/turn
Card 15			
CLP	F10.5	Roll damping moment coefficient, per rad/s	
DTM	F10.5	Time increment	seconds (Note 2)
DMM	F10.5	Projectile diameter	millimeters
CAL	F10.5	Projectile length	calibers
Card 16			
TITLA	5A6	Title for card output	

See Notes at end of table.

TABLE 1. (Contd.)

Symbol	Format	Description	Units
Card 17			
NTAB	I2,8X	Table number	
VKT	F10.1	Aircraft velocity	knots
QE	F10.1	Quadrant elevation (- for dive angle)	degrees (Note 3)
TEMP	F10.1	MSL temperature	°F
ZT	F10.1	Terminal or target elevation	feet (MSL)
ZO	F10.1	Firing elevation	feet (MSL)
Card 18			
RIX	F10.7	Axial moment of inertia	lb-inch ²
RIY	F10.7	Transverse moment of inertia	lb-inch ²
WTO	F10.7	Projectile weight	pounds
VO	F10.2	Projectile velocity	ft/s
PINT	F10.2	Printout skip	(Note 4)
Card 19			
JRUN	I2	Additional runs Last run ≤ 0 Additional runs > 0 For additional runs, repeat cards 16, 17, 18, & 19	

NOTES:

1. Drag table scaling constant multipliers. These are normally set at 1.0, i.e., the drag table applies to the round in question. If no drag table is available for the projectile, these scaling factors can be applied to drag tables for similar rounds. In that case, the FFD applies to the drag coefficient data, and FFM applies to the static moment coefficient data.
2. The time increment "DTM" is optional, but normally, a time increment of 0.1 second has been found adequate.
3. Quadrant elevation "QE" refers to the gun elevation relative to the horizontal. A positive QE represents elevation above the horizontal, and a negative QE represents a negative (down) elevation or dive angle.
4. The printout skip "PINT" permits printout at selected time intervals.

CARD OUTPUT

The program is designed to automatically prepare a card deck for use as input to various plotting routines. This card output prepares one card per data "line" in the main trajectory tables, and includes 10 variables, as follows: time, horizontal range, altitude (MSL), slant range, velocity, kinetic (impact) energy, trajectory drop, spin, impact angle, and gyroscopic stability factor (see Table 2).

These 10 variables are mainly of concern to the projectile designers and weapon effectiveness analysts, but the additional trajectory drop (trajectory drop relative to the line of sight for the gun) is of special interest to those concerned with gunsights and related effects.

Where this card output feature is not required, it can easily be eliminated by removing card No. 19, 130, and 277 in the main program.

The use of separate output decks for computer runs was found extremely valuable for parametric studies where comparison plots could be prepared for various combinations of calibers and/or projectile characteristics. Also, since various combinations of the 10 variables can be plotted, these card outputs are extremely flexible in fulfilling special plotting requirements.

TABLE 2. Card Output.

Symbol	Format	Description	Units
Card 1			
TITLA	5A6	Title for identification	
Card 2-N			
TIME	F7.2,1X	Time	seconds
X	F7.0,1X	Horizontal range	feet
Z	F7.0,1X	Altitude (MSL)	feet
SLNT	F7.0,1X	Slant range	feet
V	F6.1,1X	Velocity	ft/s
ENG	F8.0,1X	Kinetic energy	ft-lb
DH	F6.1,1X	Trajectory drop	feet
RPS	F7.0,1X	Spin	rev/s
TTT	F6.2,1X	Impact angle (versus horizontal)	degrees
SG	F6.2	Gyroscopic stability factor	

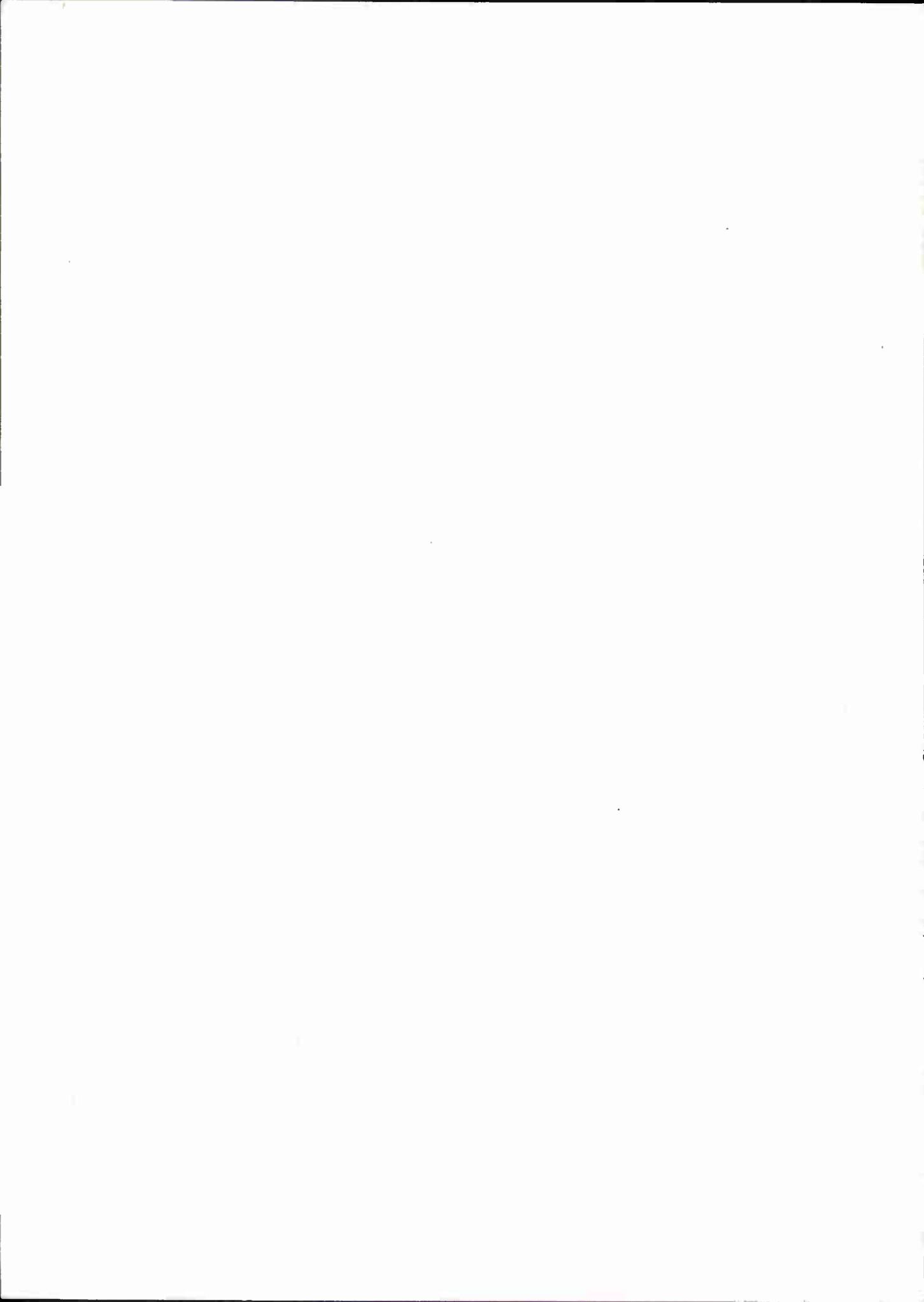
TYPICAL TRAJECTORY TABLE OUTPUT

The program is primarily designed to prepare trajectory tables in final form and ready for publication in reports, or for immediate use by projectile designers and weapon system effectiveness analysts. These tables print out the trajectory data, a total of 14 variables, in an easily read double-line format, at preset time increments. In the trajectory table example shown in Appendix E, a time increment of 0.1 s was used, but this time increment can be changed merely by changing the printout skip ("PINT") in card 18 of the input data deck.

The program as listed uses an altitude cutoff; i.e., the program stops when it reaches the specified target altitude. Changes can easily be made by qualified programmers for special requirements, such as maximum range cutoff; but, for most cases, the altitude cutoff has been satisfactory.

When the program reaches the cutoff point, it calculates the exact time, slant range, velocity, impact angle, spin, and the gyroscopic stability factor. This is then printed out at the end of the trajectory table.

A typical example of the trajectory table output is shown in Appendix E, which is the output generated by the input listed in Appendix F. This example also shows the additional data printed at the end of each trajectory table, including ballistic data, drag table, and legend.

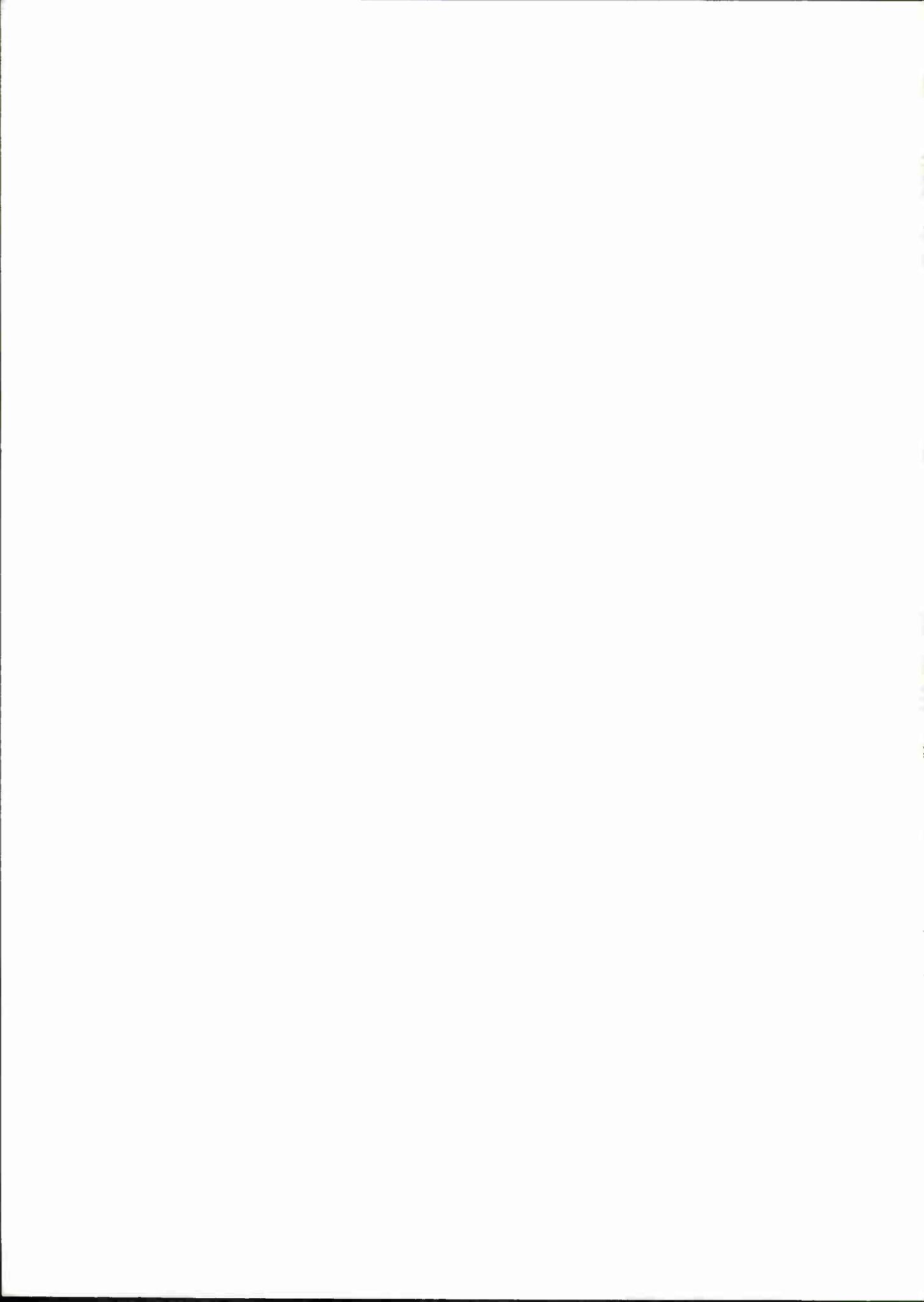


BIBLIOGRAPHY

Army Materiel Command. *Design for Control of Projectile Flight Characteristics*. Washington, D.C., Headquarters AMC, September 1966. AMC Engineering Handbook Series No. 242.

Naval Weapons Center. *Calculations of Gyroscopic Stability Factor for Various 20mm General Purpose Projectile (GPP) Configurations*, by John E. Peterson. China Lake, Calif., NWC, 27 February 1966. (NWC TN 3011-109.)

Naval Weapons Center. *NWC Trajectory Computer Program; verification of*, by J. E. Peterson. China Lake, Calif., 27 July 1973. (Memorandum 5115/JEP:pas, Serial 75.)



Appendix A
PROGRAM GLOSSARY

<u>Program</u>	<u>Definition</u>	<u>Symbol</u>	<u>Unit</u>
ACC	Projectile acceleration along trajectory at start of Δt	A_o	ft/s ²
ACCT	Projectile acceleration along trajectory at end of Δt	A_t	ft/s ²
CAL	Projectile length	cal	calibers
CD	Drag coefficient	C_D	
CDD2	Yaw-drag coefficient, per rad ²	$C_{D\delta} 2$	
CDO(I,1)	Mach number element in drag table (see text)	M	
CDO(I,2)	Drag coefficient element in drag table (see text)	C_{D_o}	
CDH	Tangent of angle theta	$\tan \theta$	
CG	Center of gravity, from base	CG	inches
CLP	Roll damping moment coefficient, per rad/s	C_{1p}	
CM	Static moment coefficient, per rad (interpolated)	$C_{M\alpha}$	
CMA	Static moment coefficient, per rad (table input)	$C_{M\alpha}$	
CMA(I,1)	Mach number element in drag table (see text)	M	
CMA(I,2)	Static moment coefficient, per rad in drag table	$C_{M\alpha}$	
D	Maximum body diameter	d	feet
DH	Trajectory drop		feet
DIST	Arc distance along trajectory	s	feet

<u>Program</u>	<u>Definition</u>	<u>Symbol</u>	<u>Unit</u>
DMM	Projectile diameter	mm	millimeters
DRAG	Projectile drag	D	pounds
DS	Arc distance traveled during Δt	ΔS	feet
DT	Length of time increment	Δt	seconds
DTM	Time increment (input)	Δt	seconds
ENG	Kinetic energy	KE	ft-lb
FFD	Scaling ratio for drag curve (see text)		
FFM	Scaling ratio for drag curve (see text)		
GACC	Projectile acceleration along trajectory due to gravity	g_s	ft/s ²
GNU	Projectile spin	ν	rad/caliber
JRUN	Number of runs		
KEA	Rifling exit angle	ϕ_1	degrees
KEB	Rifling exit angle	ϕ_2	minutes
NTAB	Table number (printout)		
PINT	Printout counter skip		
PINTT	Printout counter		
QE	Quadrant elevation	θ	degrees
RGA	Axial radius of gyration	k_a	calibers
RGT	Transverse radius of gyration	k_t	calibers
RHO	Ratio of air densities at altitude and at sea level	ρ/ρ_o	
RH005	One-half air density at sea level at temperature T	$(1/2)\rho$	slugs/ft ³

<u>Program</u>	<u>Definition</u>	<u>Symbol</u>	<u>Unit</u>
RIX	Axial moment of inertia	I_x	lb-inch ²
RIXS	Axial moment of inertia	I_x	slug-ft ²
RIY	Transverse moment of inertia	I_y	lb-inch ²
RIYS	Transverse moment of inertia	I_y	slug-ft ²
RPS	Projectile spin	RPS	rev/s
S	Frontal area of projectile	A	ft ²
SG	Gyroscopic stability factor	s_g	
SGC	Computation constant for gyroscopic stability factor		
SLNT	Slant range		feet
TEMP	Air Temperature	T	°F
TEMPR	Ratio of standard absolute temperature to absolute air temperature		
THBAR	Average trajectory angle for Δt	$\bar{\theta}$	radians
THETA	Trajectory angle at end of Δt	θ_+	radians
THT	Sign carrying variable for surface-to-surface maximum trajectory elevation		
TIME	Time after firing	t	seconds
TITLA	Title for card output		
TTT	Theta angle converted to degrees		degrees
TWIST	Rifling twist	η	calibers/turn
V	Velocity	v	ft/s
VAO	Sea level velocity of sound at temperature T	v_{a_0}	ft/s

<u>Program</u>	<u>Definition</u>	<u>Symbol</u>	<u>Unit</u>
VBAR	Average velocity over Δt	\bar{v}	ft/s
VKT	Aircraft velocity	kt	knots
VM	Mach number	M	
VO	Muzzle velocity	v_o	ft/s
WGI	Projectile weight	gr	grains
WGR	Projectile weight	gm	grams
WS	Projectile mass	m	slugs
WTO	Projectile weight	W	pounds
X	Horizontal range	x	feet
YAW	Yaw of repose	δ_r	degrees
YR	Yaw of repose	δ_r	radians
YRC	Computation constant for yaw of repose		
Z	Projectile altitude (above MSL)	z	feet
ZF	Altitude for testing end of trajectory	z_f	feet
ZO	Gun altitude (above MSL)	z_o	feet
ZT	Target altitude (above MSL)	z_t	feet

Appendix B
PROGRAM LISTING

This Appendix contains the program listing. The input deck is described separately.

```

-RUN 145112,XXXXXX,4022TRAAX,01,299/900 PETERSUN 2505
-FOR,12,TRAXX
C  TRAJECTORY PROGRAM - JOHN L. PETERSON CODE 4922
C DIMENSION T(12)
C DIMENSION COO(12,12), SMA(.12,.12)
C INPUT DATA
D0 11 I = 1,12
      KLAU(5,I1) N, COO(1,1), COO(1,2), SMA(1,1), SMA(1,2)
11  CONTINUE
11  FORMAT(1E,0,4F1.0)
11  FORMAT(0A,12,0A,12,0A,3)
11  READ(5,12) KEA,KL3,CC
11
11  READ(5,305) FFD,FFM,CDD2,TWIST
11  READ(5,305) CLP,DTM,DMM,CAL
11  READ(5,304) TITLA
11
11  FORMAT(5A6)
11  FORMAT(4F1.5)
11  READ(5,310) NTAU,VKT,GE,TEMP,L1,ZO
11  FORMAT(12.6A,2I10)
11  REAL(5,311) RIX,RIV,WIC,VU,PRINT
11  WRITE(7,706) TITLA,NIA5
11
11  FORMAT(5A6,2A,5TABLE,12)
11
11  FORMAT(3F10.7,2F10.2)
11  CONTINUE
11  INITIALIZATION
C
C D = DMIN * 0.003200832
C TEMP = 510.0 / (459.0 + TEMP)
C VAC = 1116.0 / (TEMP**0.5)
C RHOUB = 0.004105*TEMP
C WS = WTC/32.0/174
C WS = SQRT(WS)
C RIXS = RIX/(32.0*174*144.0)

```

```

R1Y5 = R1Y/(32*174*144*c)
RKAY = 1.0/(D*a*c)
RCA = RKAY * SUR(RIX5)
RST = RKAY * SUR(R1Y5)
PINIT = U.U
NU = U
TIME = U.U
X = U.U
UH = U.U
DIST = U.U
SLEN = U.U
THT = QE
Z = ZO
HT(QE) 21,22,23
21 ZR = ZI
GO TO Z3
22 ZR = ZU
23 Z = *(B54*D)**Z
WU1 = 7000.*U*WTU
WUR = 455.0324*WTU

THETA = U.U1745329*GT
CUM = TAN(HTA)
V = VU + (1.0684*VKT)
SGC = RG*A**4/(4.0*RHOU5**U*RGT**2)
UNU = (6.02832/TW151)*(VU/V)
RPS = GNO * V * Z*425526
YRC = 32.017*ROA**2/(RHOU5**c)
MAIN PROGRAM
WRITE(6,14) NAD
WRITE(6,15) ZU,UE

```

61	WRITE(6,10) VKI, TELM	
62	14 FURMAT(161,78,3HCLM&,78,3HENG)	
63	15 FURMAT(161,78,3HCLM&,78,3HENG)	
64	16 FURMAT(161,78,3HCLM&,78,3HENG)	
65	17 FURMAT(161,78,3HCLM&,78,3HENG)	
66	18 FURMAT(161,78,3HCLM&,78,3HENG)	
67	19 FURMAT(161,78,3HCLM&,78,3HENG)	
68	20 FURMAT(161,78,3HCLM&,78,3HENG)	
69	21 FURMAT(161,78,3HCLM&,78,3HENG)	
70	22 FURMAT(161,78,3HCLM&,78,3HENG)	
71	23 FURMAT(161,78,3HCLM&,78,3HENG)	
72	24 FURMAT(161,78,3HCLM&,78,3HENG)	
73	25 FURMAT(161,78,3HCLM&,78,3HENG)	
74	26 FURMAT(161,78,3HCLM&,78,3HENG)	
75	27 FURMAT(161,78,3HCLM&,78,3HENG)	
76	28 FURMAT(161,78,3HCLM&,78,3HENG)	
77	29 FURMAT(161,78,3HCLM&,78,3HENG)	
78	30 FURMAT(161,78,3HCLM&,78,3HENG)	
79	31 FURMAT(161,78,3HCLM&,78,3HENG)	
80	32 FURMAT(161,78,3HCLM&,78,3HENG)	
81	33 FURMAT(161,78,3HCLM&,78,3HENG)	
82	34 FURMAT(161,78,3HCLM&,78,3HENG)	
83	35 FURMAT(161,78,3HCLM&,78,3HENG)	
84	36 FURMAT(161,78,3HCLM&,78,3HENG)	
85	37 FURMAT(161,78,3HCLM&,78,3HENG)	
86	38 FURMAT(161,78,3HCLM&,78,3HENG)	
87	39 FURMAT(161,78,3HCLM&,78,3HENG)	
88	40 FURMAT(161,78,3HCLM&,78,3HENG)	
89	41 FURMAT(161,78,3HCLM&,78,3HENG)	
90	42 FURMAT(161,78,3HCLM&,78,3HENG)	

```

60 TO 40          91
43 CD = FHD*CD    92
44 IF (CMA(1<,1)-VN) < 400    93
45 CM = CMA(1<,2)    94
50 TO 55          95
46 IF (CMA(1,1)-VM) > 401,401    96
47 CM = CMA(1,2)    97
50 TO 55          98
48 I = 2          99
49 DIFF = VM - CMA(1,i)    100
50 TO 55          101
51 CM = CMA(1,2)+IF*(CMA(1,2)-CMA(1-i,2))/(CMA(1,i)-CMA(1-i,1))    102
52 CM = RFM*CM    103
53 YAW = (YRC*W*GUN/(RHO*UN**2))*COS(TILT)    104
54 YAW = YR/0.1/4.27    105
55 UKAO CALCULATION    106
56 CD = CD + UN2*YR**2    107
57 CL = -32.17*SIN(TILT)    108
58 UKAO = RHO*D*KHOU(V**2*CL)    109
59 ALL = UNL - UKAO/WS    110
60 ENO = UN2*W2*(V**2)    111
61 DTM = DTM    112
62 TILT FOR SURFACE FINE    113
63 TILT = THEIA*0.01324    114

```

```

56 IF (INI*TRAJ) / U, / V, / W, / X, / Y, / Z
57 C
58 PRINT=PRINT+1
59 PRINT = PRINT - 100
60 C
61 PRINT = PRINT / 64,004
62 C
63 WRITE(6,81) TIME,X,DELNI,V,DR,CM,ENO
64 FORMAT(12X,F7.2,2H0.0,1H0.0,1H0.0,1H0.0)
65 WRITE(6,82) ITT,DUKAS,YAW,VW,RP,DP,CP
66 FORMAT(12X,F7.2,2H0.0,1H0.0,2H0.0,1H0.0,1H0.0)
67 WRITE(7,707) TIME,X,DELNI,V,DR,CM,ENO,ITT,DP
68 C
69 FORMAT(F7.2,IX,F7.2,IX,F7.2,IX,F7.2,IX,F7.2,IX)
70 IFO=1,1X,F7.2,1X,F7.2,1X,F7.2,1X,F7.2,1X,F7.2
71 NU = NU + 1
72 C
73 WRITE(6,84) NTAB
74 FORMAT(12X,2HNTAB)
75 WRITE(6,12) ZO, UC
76 WRITE(6,16) VKT, TEMP
77 NU = 0
78 PRINT = PRINT
79 C
80 WRITE(6,150)
81 WRITE(6,160)
82 CONTINUE
83 C
84 DRAS = DRAS*(1.0+Z*ACCU/V)
85 ACCU = GALL - DUKAS/W
86 VBAR = V + (ACCU + ACCU)*DU/4.0
87 DU = VBAR*D
88 V = 2.0*V*VBAR-V
89 C
90 FORMAT(12X,2HNTAB)
91 WRITE(6,85) (NU-T)/13.0
92 C
93 WRITE(6,151)
94 WRITE(6,161)
95 C
96 CALCULATIONS FOR INLET TRAJECTORY INCREMENT
97 C
98 C
99 C
100 C
101 C
102 C
103 C
104 C
105 C
106 C
107 C
108 C
109 C
110 C
111 C
112 C
113 C
114 C
115 C
116 C
117 C
118 C
119 C
120 C
121 C
122 C
123 C
124 C
125 C
126 C
127 C
128 C
129 C
130 C
131 C
132 C
133 C
134 C
135 C
136 C
137 C
138 C
139 C
140 C
141 C
142 C
143 C
144 C
145 C
146 C
147 C
148 C
149 C
150 C

```

```

DIST = DIST + DS      151
TIME = TIME + DT     152
THETA = THETA        153
INDAK = THEIA - 16.0*DS*(TIME(A)*DI/VBAR) 154
X = X + DS*DS*(INDAK) 155
Z = Z + DS*DSIN(INDAK) 156
DH = X * CDH + ZD - Z 157
SLNT = SQR((((ZD - Z)**2)+(A**2)) 158
THEIA = THEIA - 32.17*DS*(TIME(DAR)*DI/VBAR) 159
GDU = GDU*(1.0+(0.04*CLP/(W0*KD*KA**2))-ACUT)*DT/V) 160

C   RPS (REV/SEC) = GDU * V * 304.8006 / (2PI * ZUOU) 161
RPS = GDU * V * 2.42E-02 162
C   IEST FOR END OF TRAJETOURI 163
IF(L-ZR) 0/0.74 164
SAFETY - MAX TIME OR LENGTH 200 SECONDS 165
IF(ZOO.0-TIME) 0/0.67,31 166
END OF FLIGHT CALCULATION 167
C   67 DS = (Z-T-Z)/SIN(THETA) 168
TIME = TIME + DS/V 169
X = X + DS*DS*(TIME(A)) 170

SLNT = SQR(((ZD - ZT)**2)+(A**2)) 171
THEIA = THEIA*0.1/4.25E-02 172
WRITE(6,93) 173
93 FORMAT(14X,OHITIME,DC9.4A,BPRKANE,FT,*,A,
17MVL,RP5,4A,DMTRL,CA9.2A,4HCPLIN,*,A,
WRITE(6,03) TIME,SLNT,V,THEIA,KP2,SG 174
83 FORMAT(12X,FT9.0,Z9.2F12.0,I9.0,U9.0,F1.2) 175
777 CONTINUE 176
177 WRITE(6,89) NIAD 177
WRITE(6,315) 178
178 WRITE(6,315) 179
179 180

```

```

312 FURMAT(1D,1D) /
  WRITE(6,320)
330 FURMAT(1D,3D,14HDELISTIC DATA/)
  WRITE(6,315)
  WRITE(6,320) DM
320 FURMAT(1D,19HPROJECTILE DIAMETER,17X,F10.2,ZA,1UHMILLIMETER//)
  WRITE(6,322) CAL
322 FURMAT(1D,17HPROJECTILE LENGTH,21X,F10.1,ZA,0MILLIMETERS//)
  WRITE(6,331) W10
  WRITE(6,332) W51
  WRITE(6,333) W52
331 FURMAT(1D,17HPROJECTILE WEIGHT,23X,F10.7,ZA,0HMOUNDED//)
332 FURMAT(5D,2,ZX,6HMOUNDED//)
333 FURMAT(5D,2,ZX,5HMOUNDED//)
  WRITE(6,366) RIX
366 FORMAT(15X,23HAXIAL MOMENT OF INERTIA,9X,F10.7,
12X,14HPOUND-INCH SG.//)
  WRITE(6,368) RIY
368 FORMAT(15X,28HIRANVERSE MOMENT OF INERTIA,4X,F10.7,
12X,14HPOUND-INCH SG.//)
  WRITE(6,334) RIA
334 FURMAT(15X,<4HAXIAL RADIUS OF CYRILLION,14X,F10.7,ZA,0HCALIBERS//)
  WRITE(6,336) ROT
336 FURMAT(15X,<9HINTERIOR RADIUS OF CYRATION,8A,F10.7,ZA,
18HCALIBERS//)
  WRITE(6,337) CO
337 FURMAT(15X,20HCENTER OF GRAVITY, FROM BASE,13X,F10.3,7H INCHES//)
  WRITE(6,338) VO
338 FURMAT(1D,15HMULLE VELOCITY,20X,F10.1,ZA,1HFT/SECOND//)
  WRITE(6,340) TWIST

```

```

340 FORMAT(15X,12NDARKEL TWIST,21X,15U,2A,13HCALIDERS/TURN//) 211
      WRITE(6,341) KEA,KEB
341 FORMAT(15X,18HRIFLING EXIT ANGLE,15X,12,9H DEGREES ,12, 212
      +8H MINUTES//)
      WRITE(6,342) CDDZ
342 FORMAT(15X,4UHYAW-URAG COEFFICIENT, PER RADIAN SQUARED, 213
      18X,FLU•1//)
      WRITE(6,344) CLP
344 FORMAT(15X,4UHYAW-URAG LAMPING MUMENT COEFFICIENT, PER RADIAN SQUARED, 214
      14X,FLU•4//) 215
      WRITE(6,346)
346 FORMAT(1H ,15X, 216
      152HURAB COEFFICIENT AND STATIC MUMENT COEFFICIENT TABLE//) 217
      WRITE(6,348)
348 FORMAT(2U,3HMACH,7X,3HCLU,6X,4HMACH,6X,3HCLMA//) 218
350 FORMAT(14X,FLU•2,FLU•2,FLU•3,FLU•3//)
DU 395 I=1,12 219
      WRITE(6,350) CUD(1,1),CUD(1,2),CLMA(1,1),CLMA(1,2) 220
395 CONTINUE 221
400 FORMAT(1H1,35X,6HLEGEND//) 222
      WRITE(6,315)
401 FORMAT(15X,4HTIME,11X,23HTIME OF FLIGHT, SECONDS//) 223
402 FORMAT(15X,1HX,14X,22HHORIZONTAL RANGE, FEET//) 224
403 FORMAT(15X,4HDIST,11X,17HSLANT RANGE, FEET//) 225
404 FORMAT(15X,1HV,14X,21HVELOCITY, FEET/SECOND//) 226
405 FORMAT(15X,2HUN,15A,10GRAVITY DROP, FEET//) 227
406 FORMAT(15X,2HUN,12X,25MRA,12X,25MRA MUMENT COEFFICIENT//) 228
      
```

407	FORMAT(11X,4H0.0E+00,11X,10H0.0000000000,11X,10H0.0000000000)	241
408	FORMAT(11X,5H1H0.0A,11X,21HIMPACT ANGLE, DEGREES//)	242
409	FORMAT(11X,1H0.0,14X,14HIMPACT ANGLE, DEGREES//)	243
410	FORMAT(11X,4H0.0E+00,11X,12H0.000,10H0.0000000000,11X,10H0.0000000000)	244
411	FORMAT(11X,3H0.0A,11X,21HYAW OF REPOSE, DEGREES//)	245
412	FORMAT(11X,4H0.0A,11X,10H0.0000000000,11X,10H0.0000000000,11X,10H0.0000000000)	246
413	FORMAT(11X,4H0.0E+00,11X,10H0.0000000000,11X,10H0.0000000000,11X,10H0.0000000000)	247
414	FORMAT(11X,4H0.0E+00,11X,10H0.0000000000,11X,10H0.0000000000,11X,10H0.0000000000)	248
415	FORMAT(11X,4HTEMP,11X,25HSURFACE (MSL) TEMPERATURE//)	249
416	FORMAT(11X,4H0.0E+00,11X,10H0.0000000000,11X,10H0.0000000000)	250
		251
	WRITE(6,4U1)	252
	WRITE(6,4U1)	253
	WRITE(6,4U2)	254
	WRITE(6,4U3)	255
	WRITE(6,4U4)	255
	WRITE(6,4U5)	256
	WRITE(6,4U6)	257
	WRITE(6,4U7)	258
	WRITE(6,4U8)	259
	WRITE(6,4U9)	260
	"WRITE(6,410)	261
	WRITE(6,411)	262
	WRITE(6,412)	263
	WRITE(6,413)	264
	WRITE(6,414)	265
	WRITE(6,415)	266
	WRITE(6,416)	267
352	CONTINUE	268
	ADDITIONAL KUNO	269
	READ(6,3U1) JRUN	270

```

    271
    272
    273
    274
    275
    276
    277
    278
    279
    280
    281
    282
    283

SUB FOKMAIL(12)
  IF(JRUN) 44494449,50<
  50<
  CONTINUE
  READ(1,304) TILLA
  READ(5,315) NTAD,VKL,GE,LEMPLZ,LU
  READ(2,311) RIA,RIR,WIU,VU,MINI
  WRITE(1,700) TILLA,NTAD
  GO TO 200
  444 WRITE(6,70)
  70 FOKMAIL(1H1,1H ////)
  END
  CALL EXIT

```

-XAT

Appendix C
PROGRAM REFERENCES TO VARIABLES

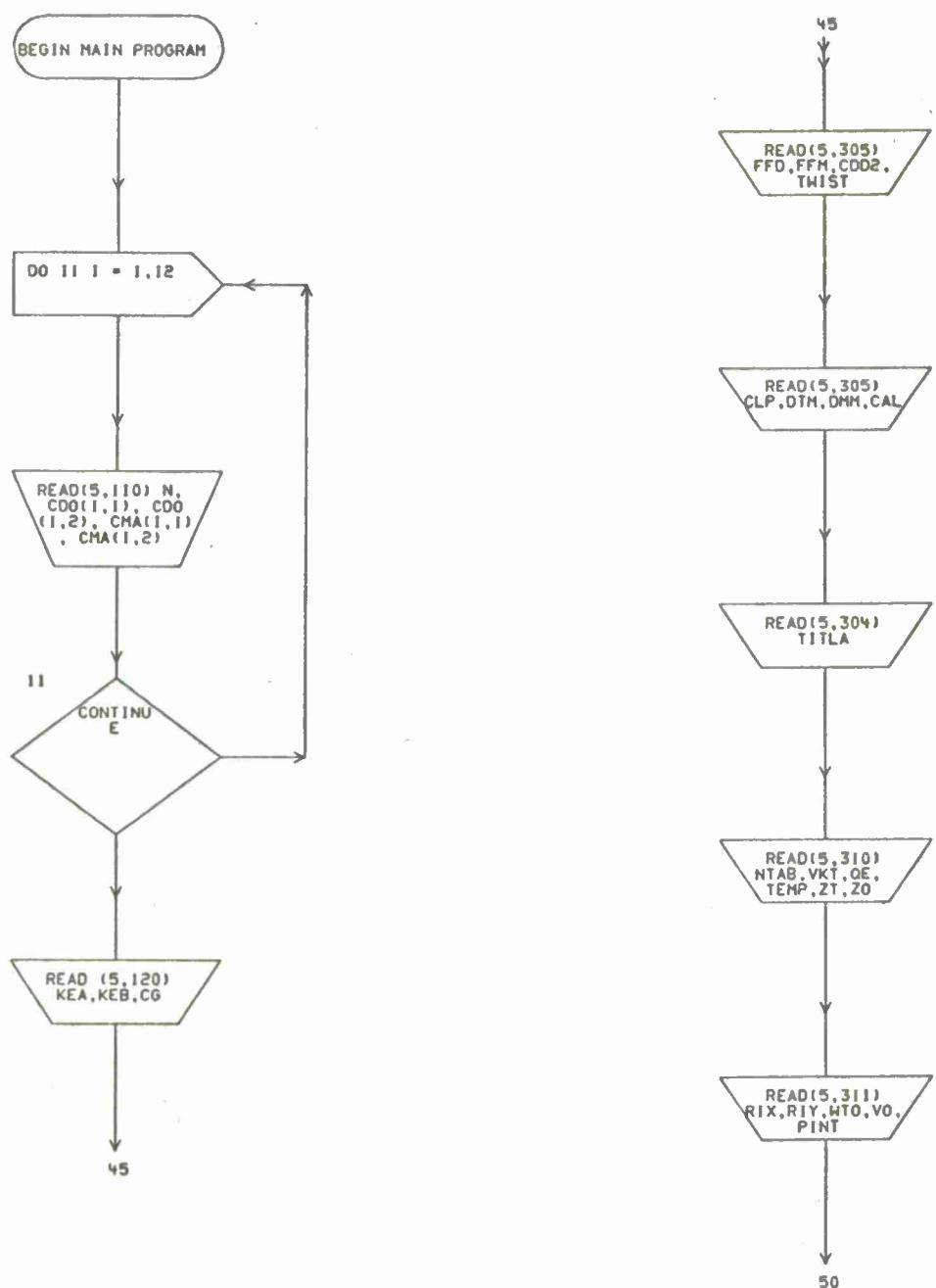
<u>Variable</u>	<u>Program line number</u>
AAC	116, 146, 148
ACCT	147, 148, 160
CAL	12, 187
CD	80, 83, 88, 92, 113, 115, 160
CDD2	11, 113, 215
CDH	52, 157
CDO	3, 6, 79, 80, 82, 83, 86, 88, 231
CG	10, 206
CLP	12, 160, 218
CM	94, 97, 102, 106, 108, 110, 126
CMA	3, 6, 93, 94, 96, 97, 100, 102, 231
D	24, 32, 48, 54
DH	39, 126, 130, 157
DIFF	86, 87, 88, 100, 101, 102
DIST	40, 151
DMM	12, 24, 185
DRAG	115, 116, 128, 146, 147, 160
DS	149, 151, 155, 156, 168, 169, 170
DT	118, 146, 148, 149, 152, 154, 159, 160
DTM	12, 118
ENG	117, 126, 130
FFD	11, 92
FFM	11, 106
GACC	114, 116, 147
GNU	55, 56, 108, 110, 160, 162
JRUN	270, 272
KEA	10, 212
KEB	10, 212

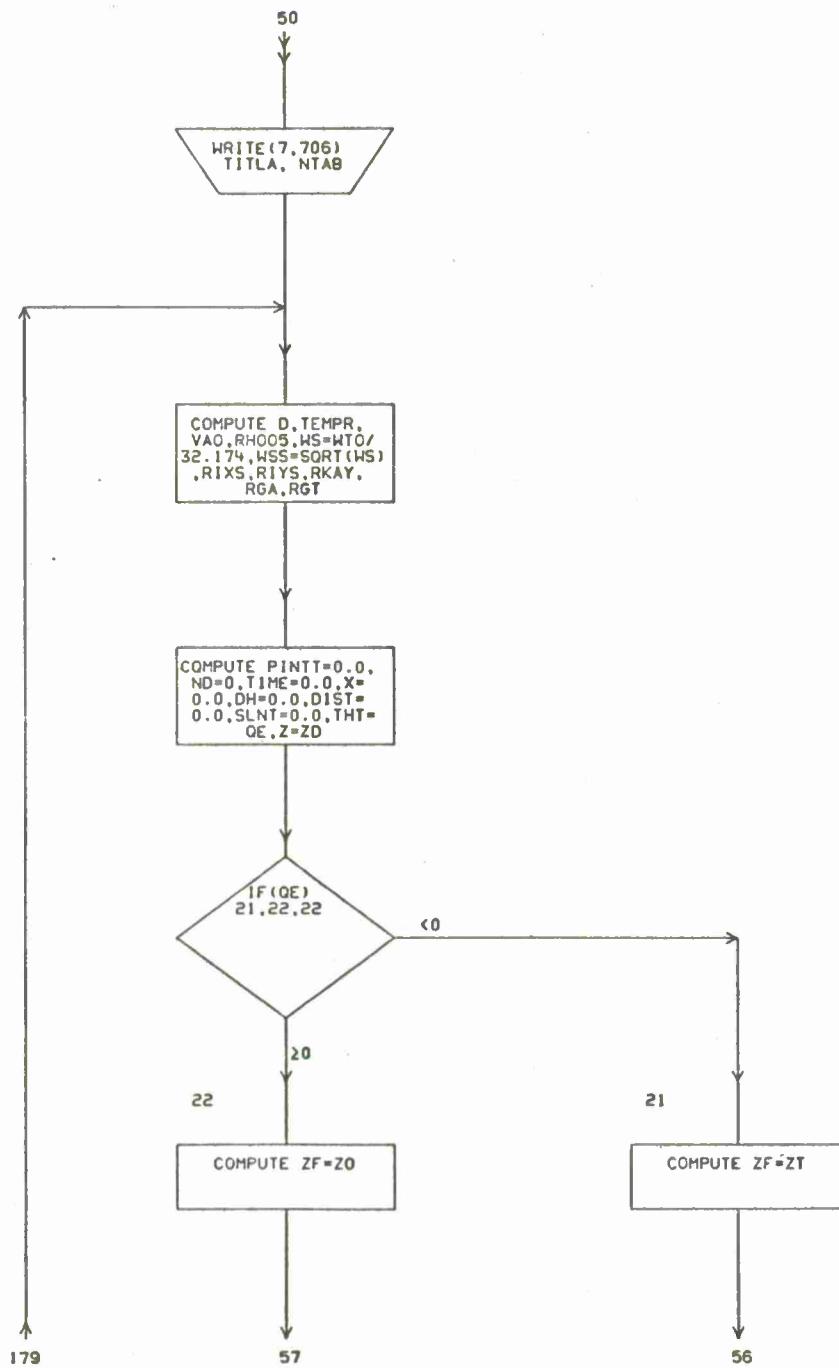
<u>Variable</u>	<u>Program line number</u>
N	6
ND	36, 133, 134, 139
NTAB	16, 19, 59, 135, 179, 221, 275, 277
PINT	18, 140, 144, 276
PINTT	35, 124, 125, 140, 144
QE	16, 42, 44, 51, 60, 137, 222, 275
RGA	33, 54, 57, 160, 201
RGT	34, 54, 203
RHO	72, 74, 108, 110, 115
RH005	27, 54, 57, 115
RIX	18, 30, 195, 276
RIXS	30, 33
RIY	18, 31, 198, 276
RIYS	31, 34
RKAY	32, 33, 34
RPS	56, 128, 130, 162, 176
S	48, 54, 57, 115
SG	108, 128, 130, 176
SGC	54, 108
SLNT	41, 126, 130, 158, 171, 176
TEMP	16, 25, 61, 138, 223, 275
TEMPr	25, 26, 27
THBAR	154, 155, 156, 159
THETA	51, 52, 110, 114, 120, 121, 153, 154, 159, 168, 170, 172, 176
THT	42, 121, 153
TIME	37, 126, 130, 152, 166, 169, 176
TITLA	2, 13, 19, 274, 277
TTT	120, 128, 130
TWIST	11, 55, 210

NWC TP 5864

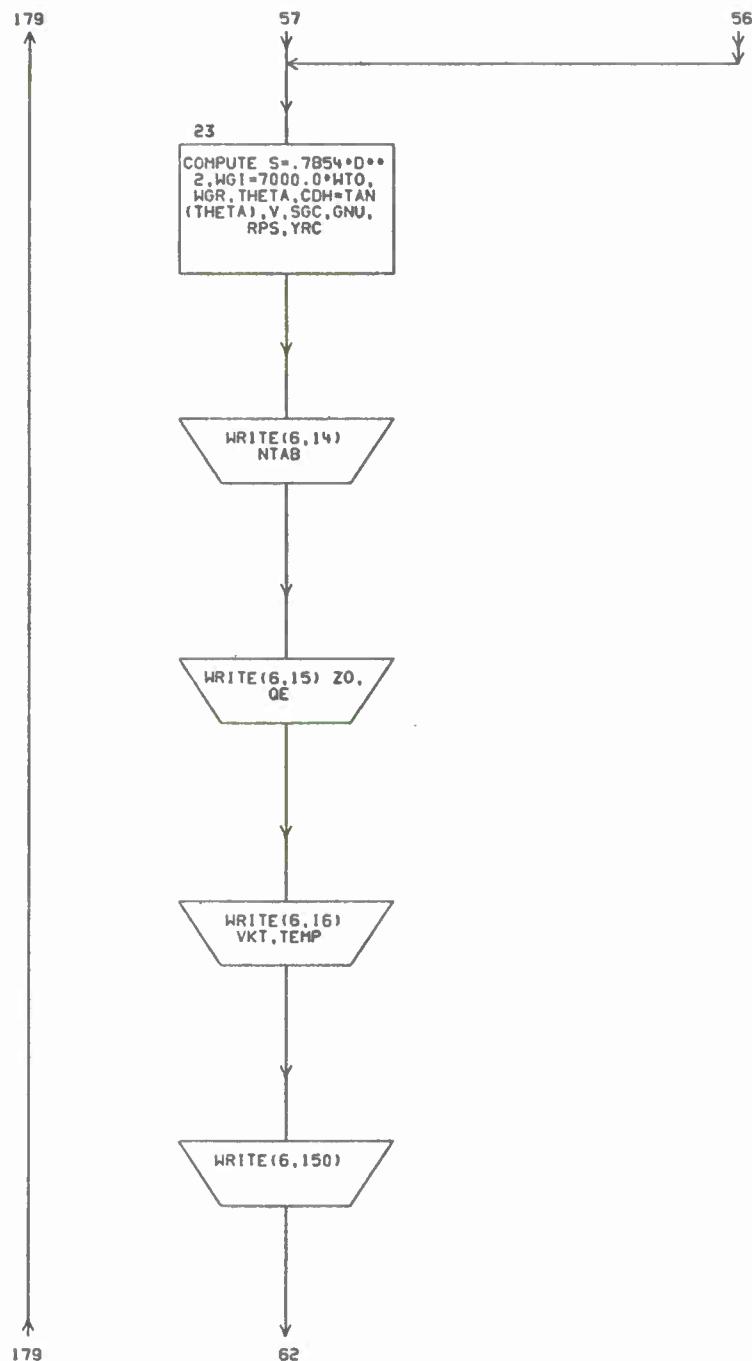
<u>Variable</u>	<u>Program line number</u>
V	53, 55, 56, 76, 78, 110, 115, 117, 126, 130, 146, 148, 150, 160, 162, 169, 176
VAO	26, 76
VBAR	148, 149, 150, 154, 159
VKT	16, 53, 61, 138, 223, 275
VM	76, 78, 79, 82, 86, 93, 96, 100, 128
VO	18, 53, 55, 208, 276
WGI	49, 190
WGR	50, 191
WS	28, 29, 108, 110, 116, 117, 147, 160
WSS	29, 32
WTO	18, 28, 49, 50, 189, 276
X	38, 126, 130, 155, 157, 158, 170, 171
YAW	111, 128
YR	110, 111, 113
YRC	57, 110
Z	43, 71, 72, 74, 75, 76, 128, 130, 156, 157, 158, 164, 168
ZF	45, 47, 122, 164
ZO	16, 43, 47, 60, 137, 157, 158, 171, 222, 275
ZT	16, 45, 122, 168, 171, 275

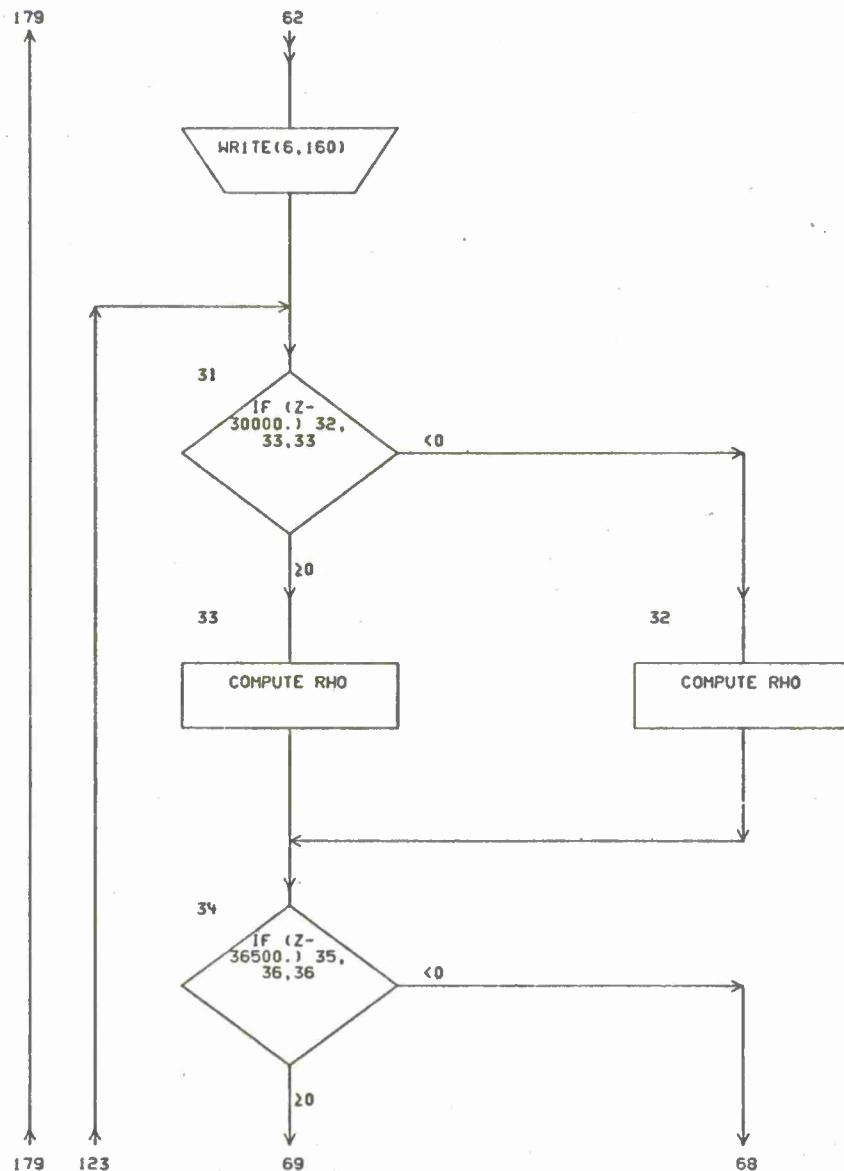
Appendix D
PROGRAM FLOW CHART

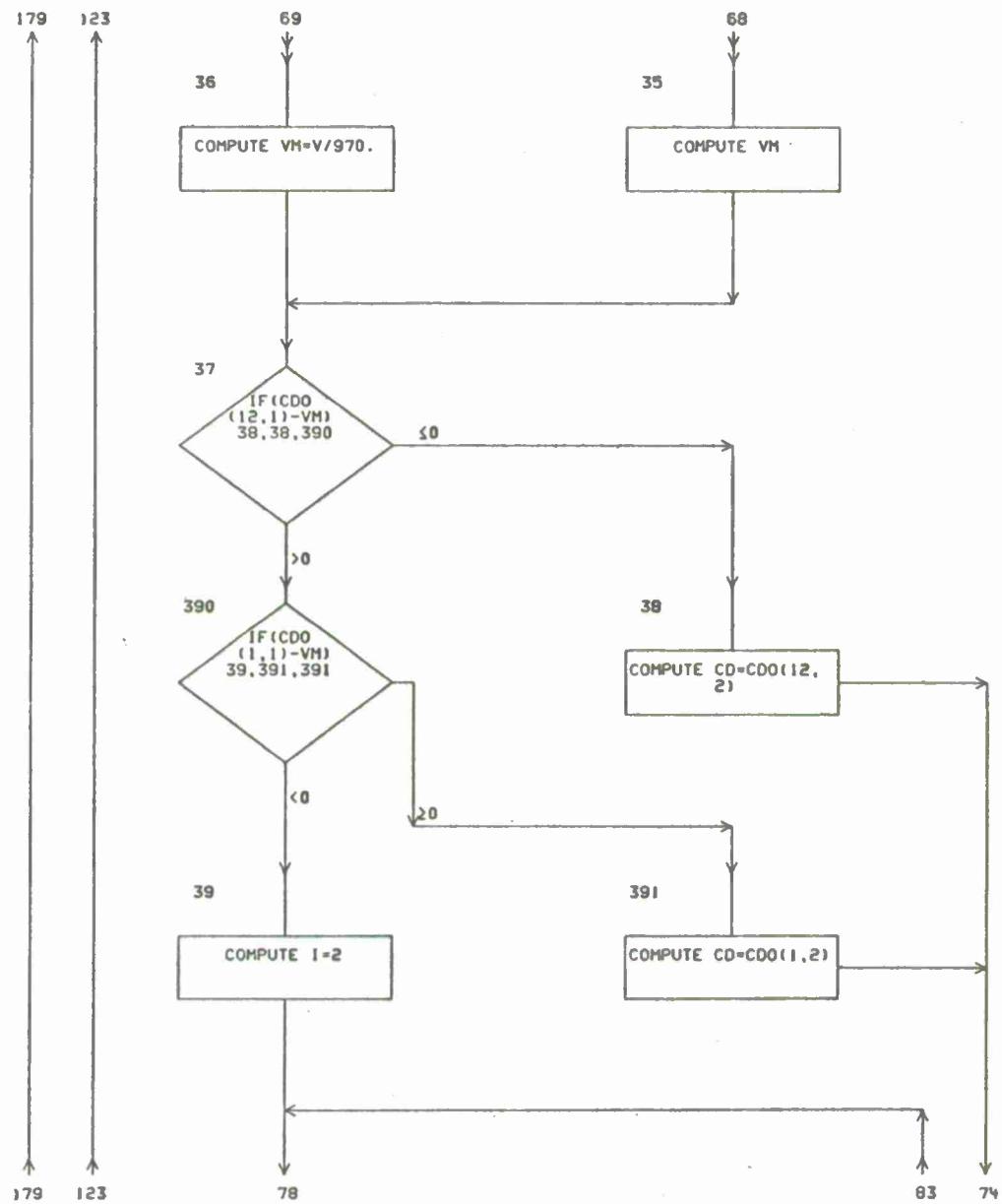


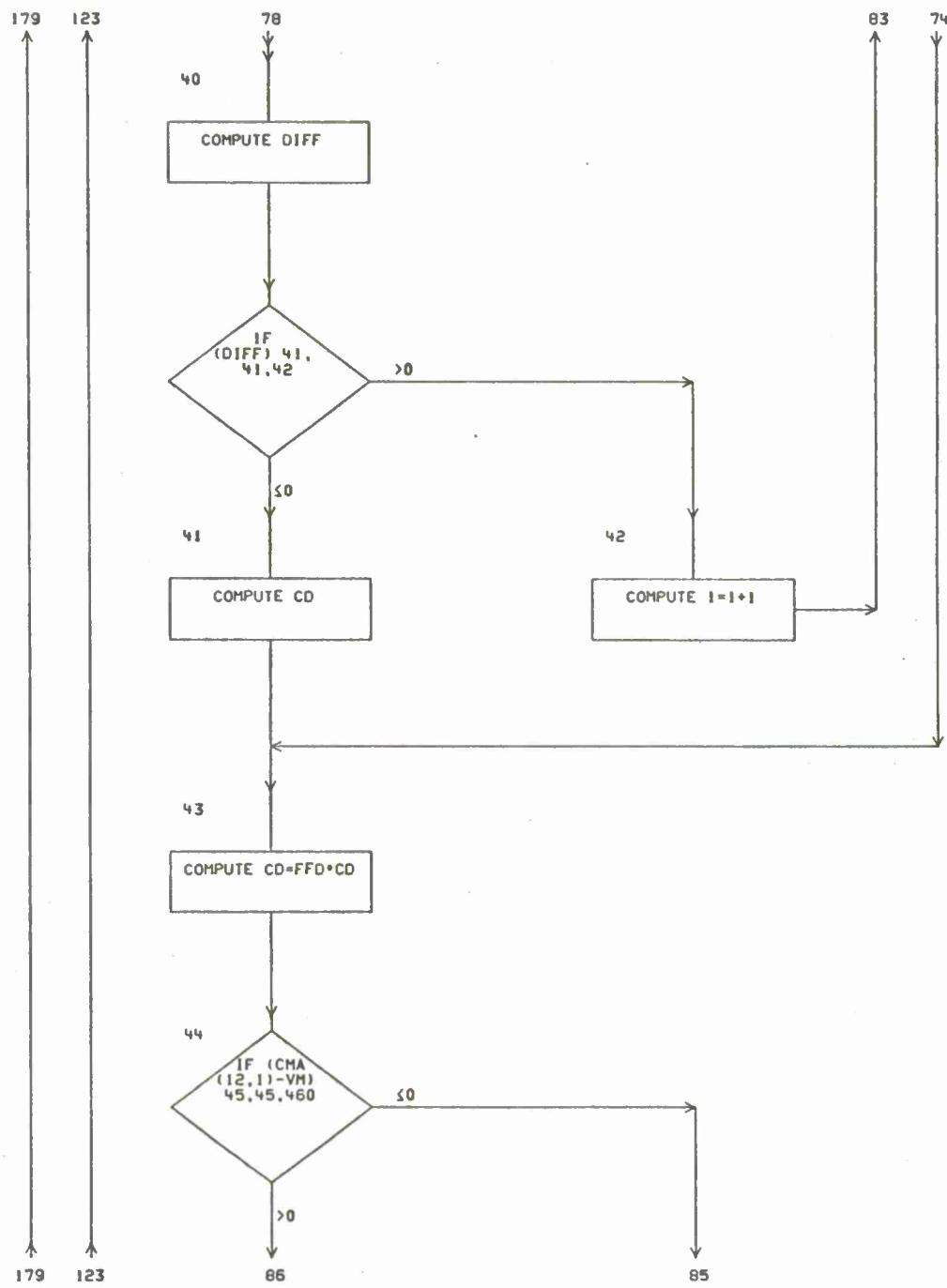


NWC TP 5864

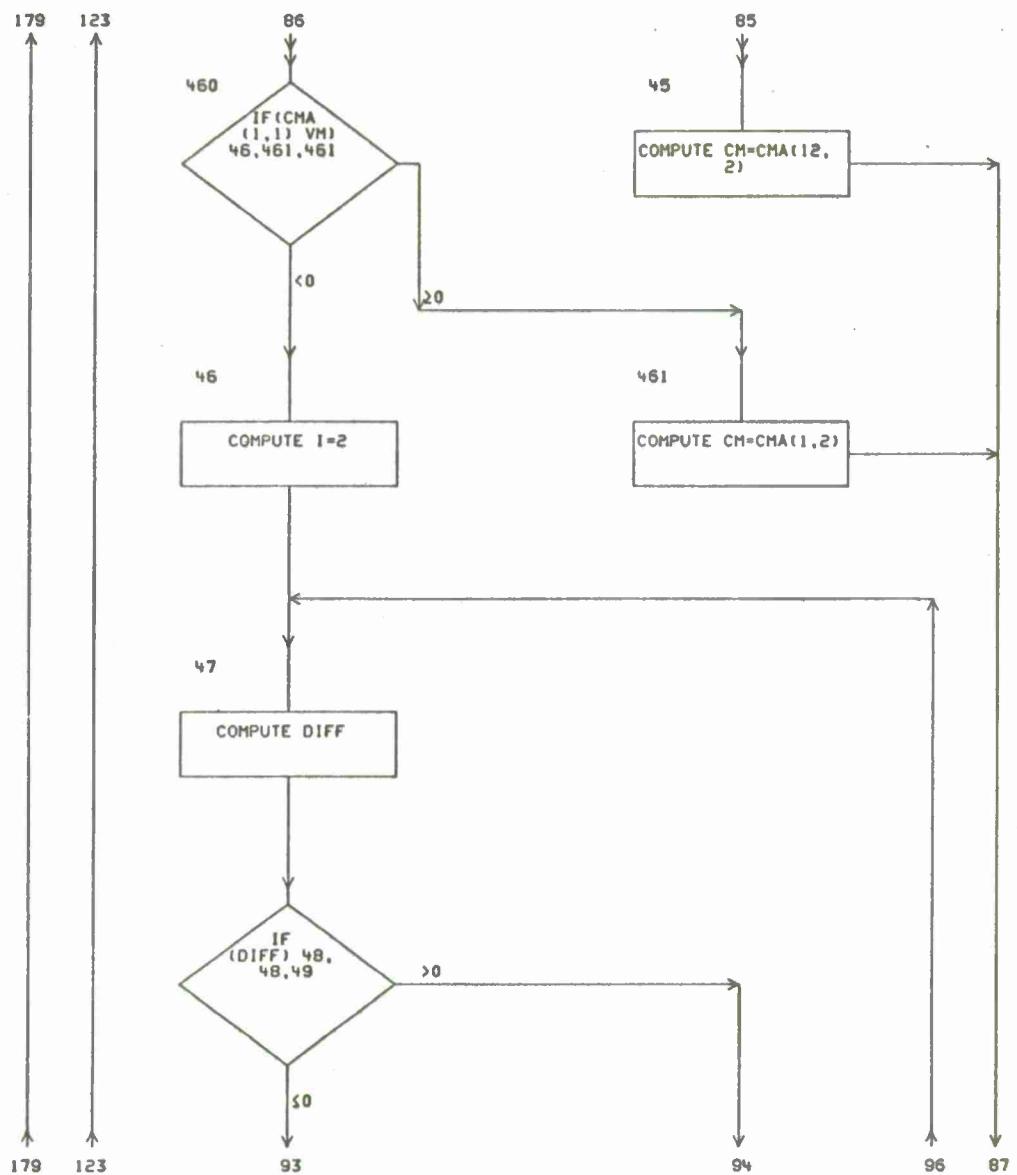


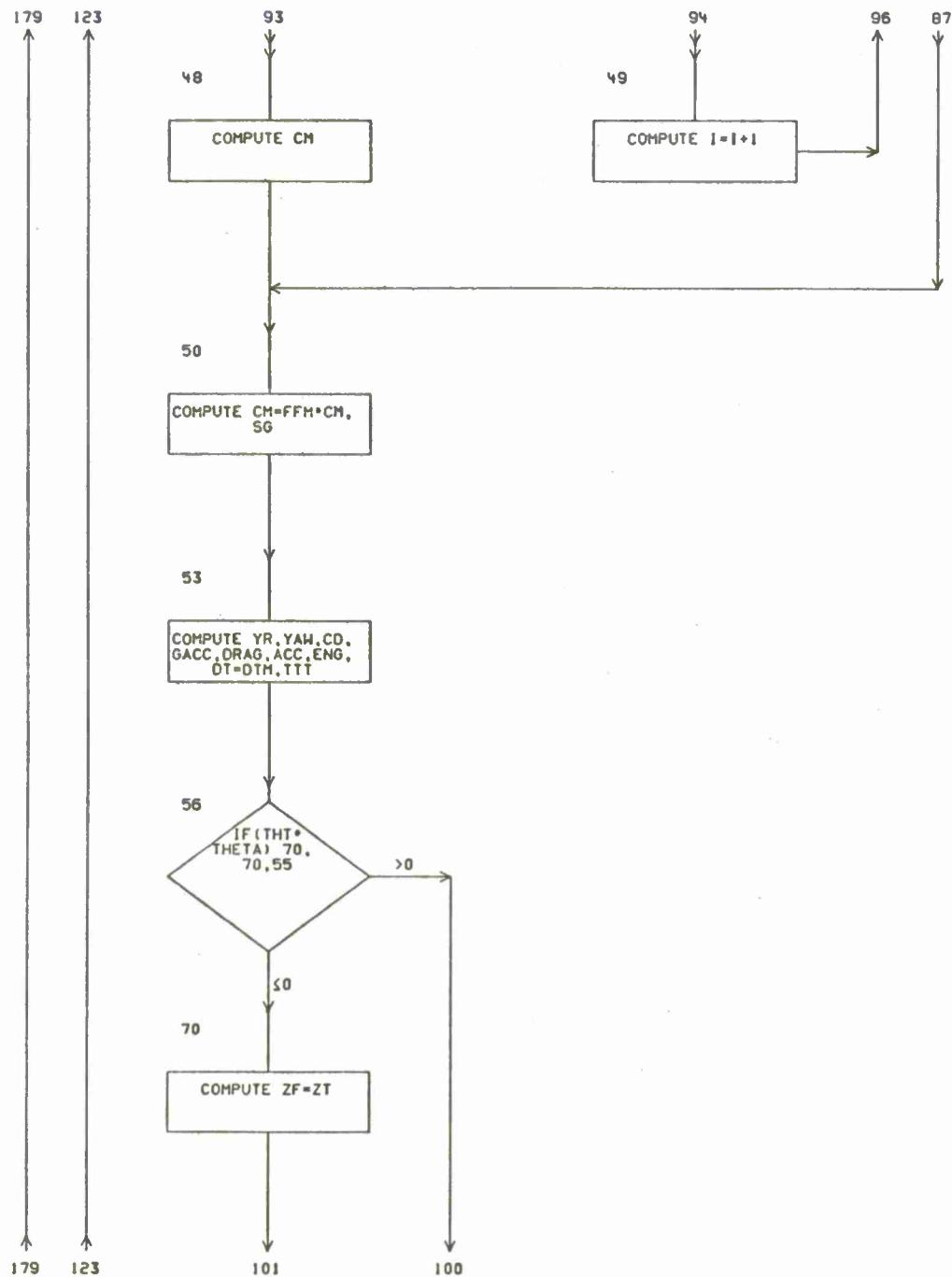




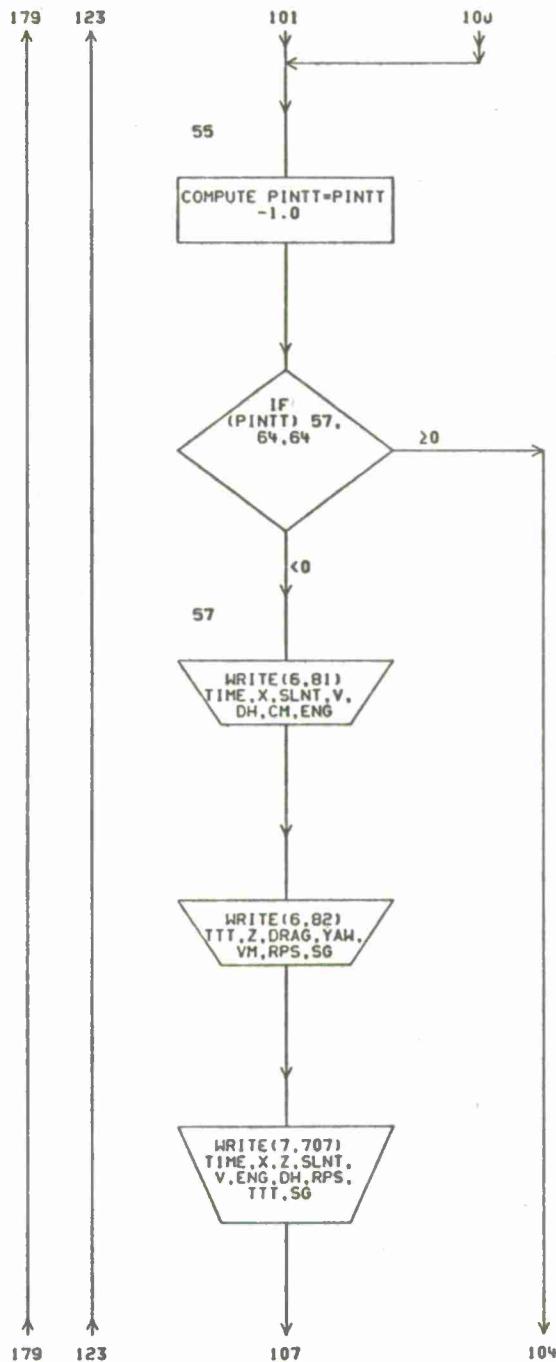


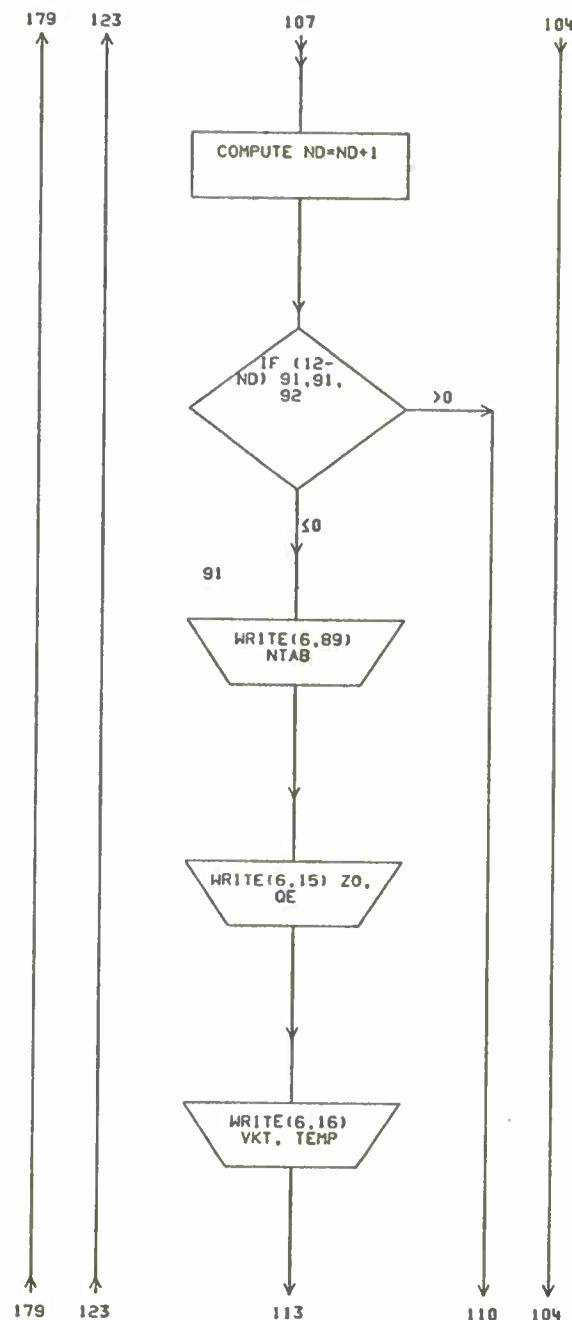
NWC TP 5864



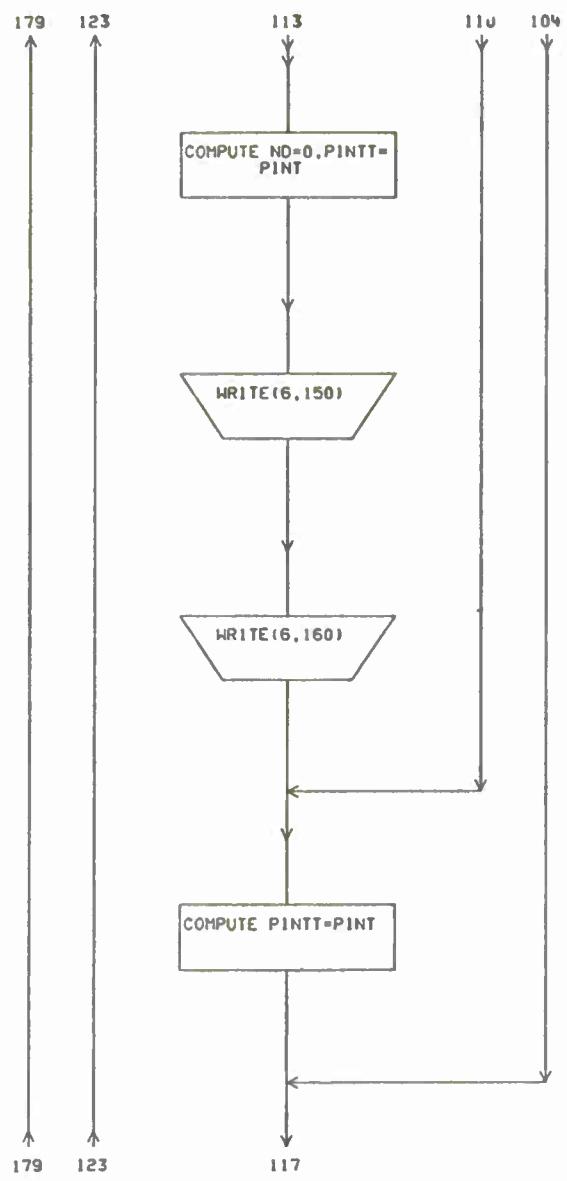


NWC TP 5864

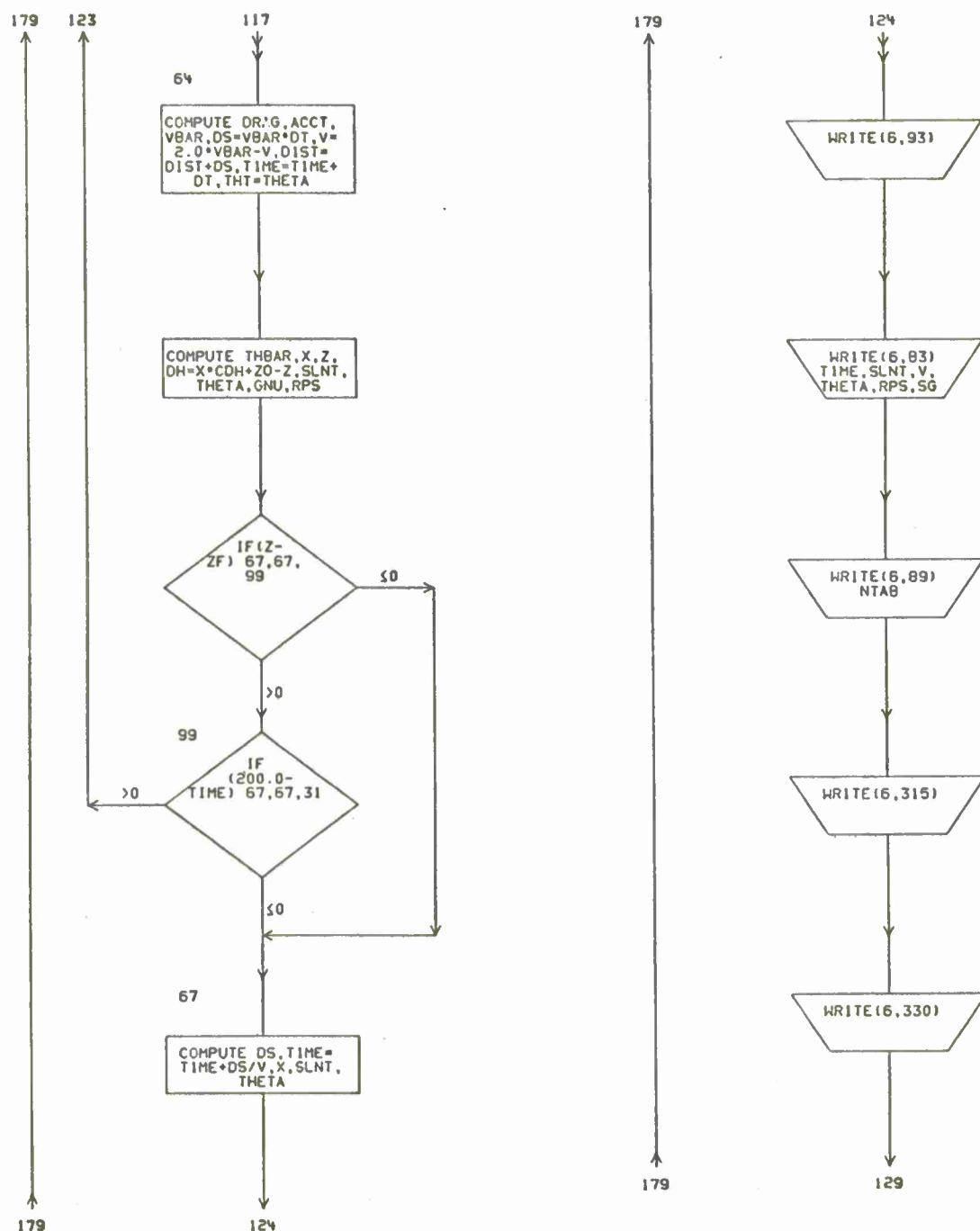




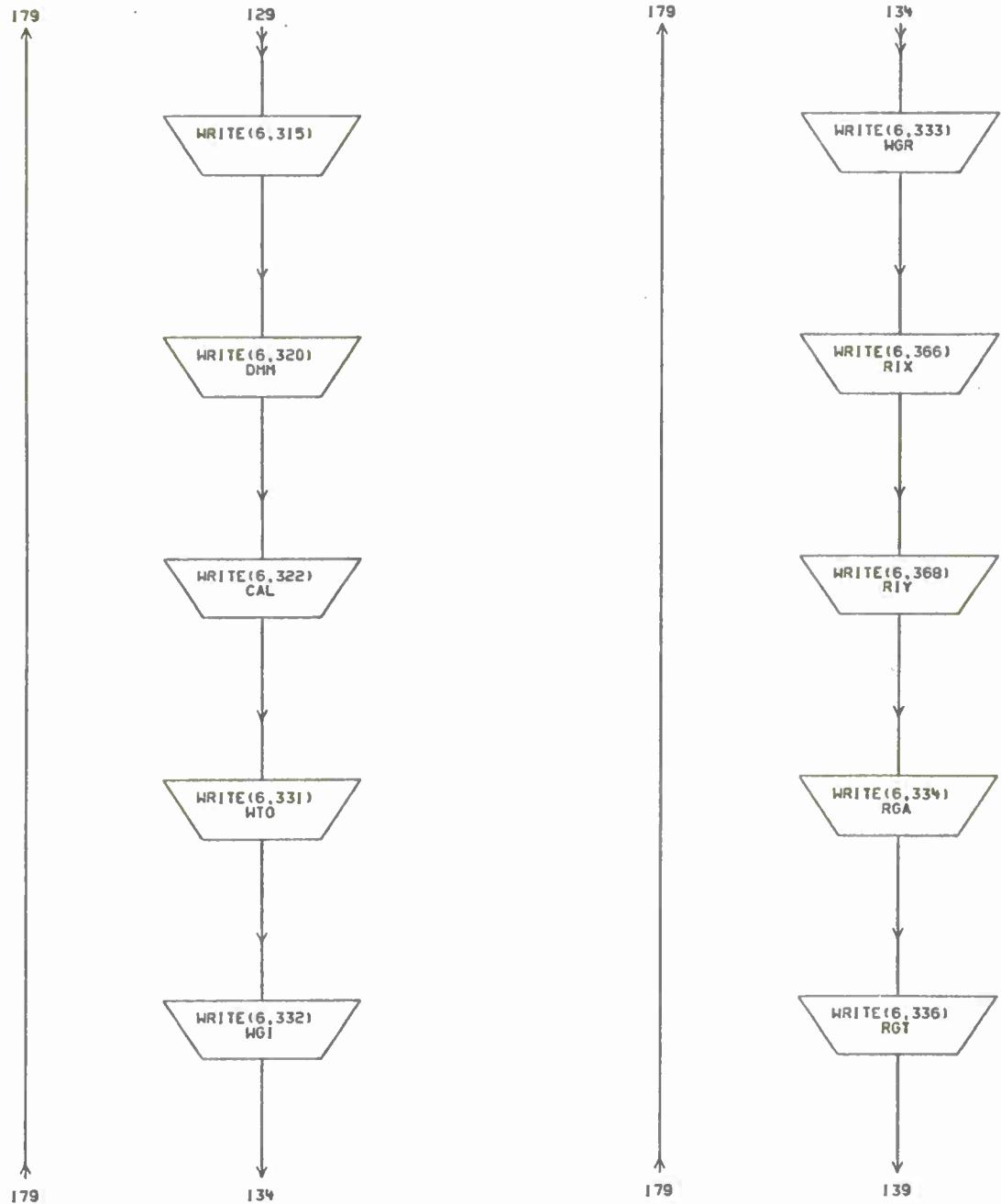
NWC TP 5864



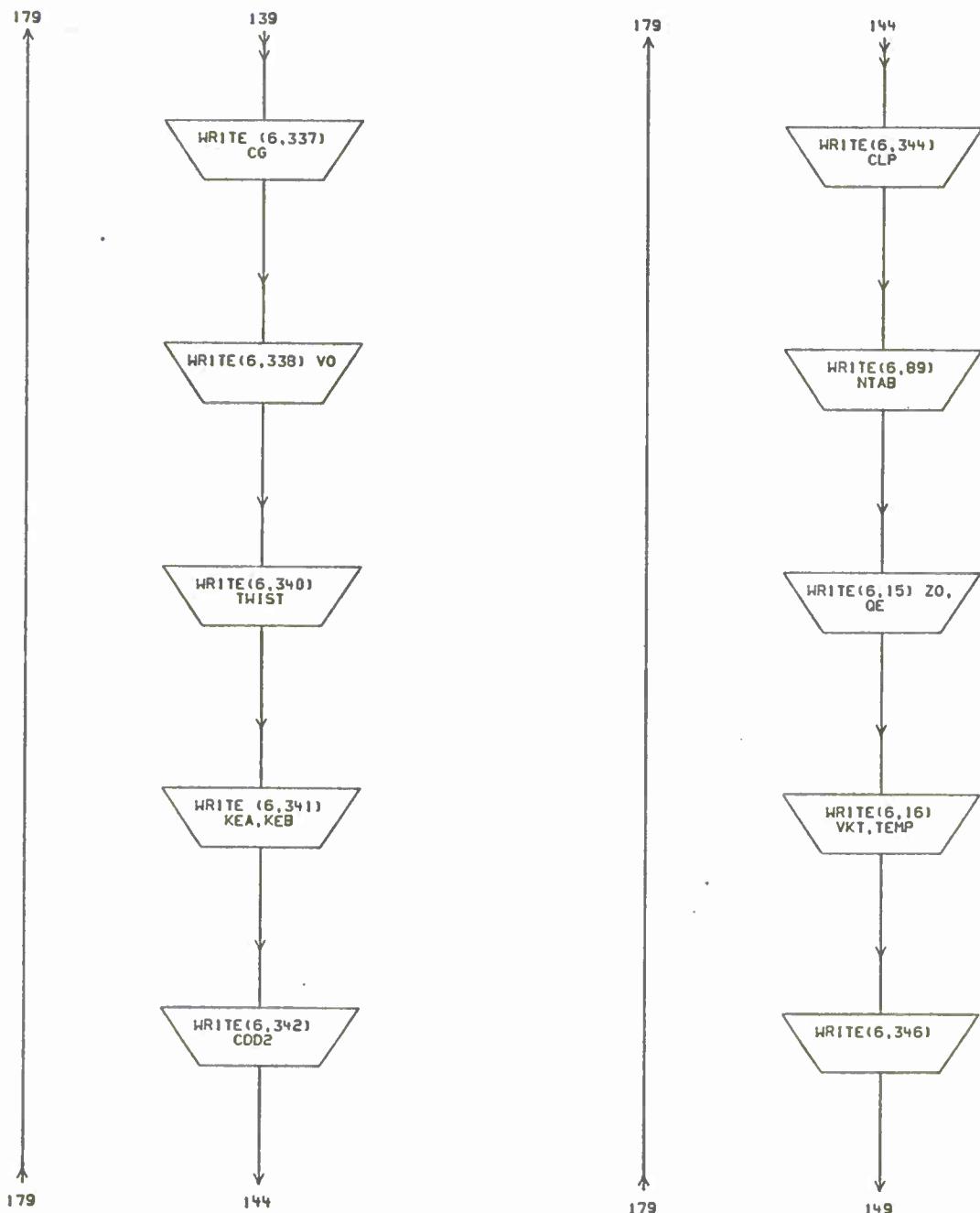
NWC TP 5864

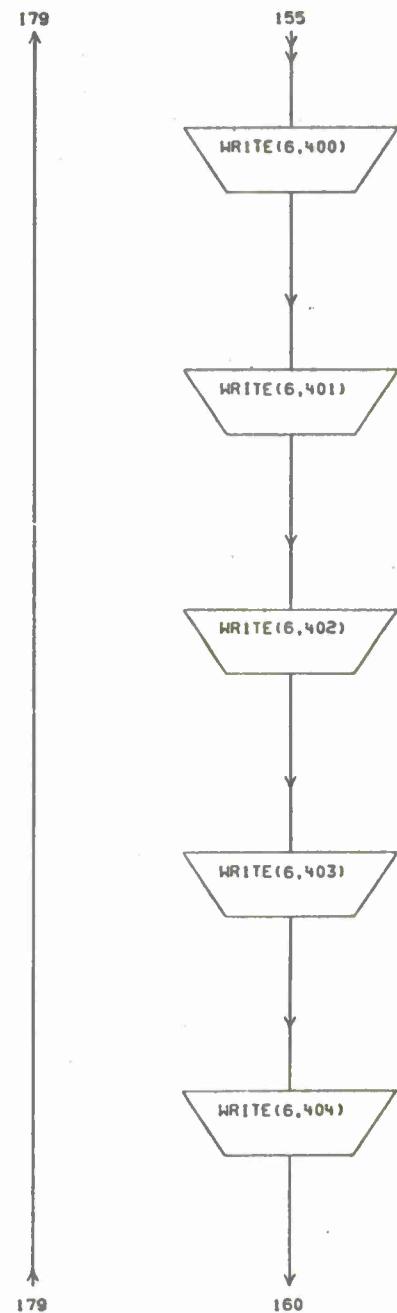
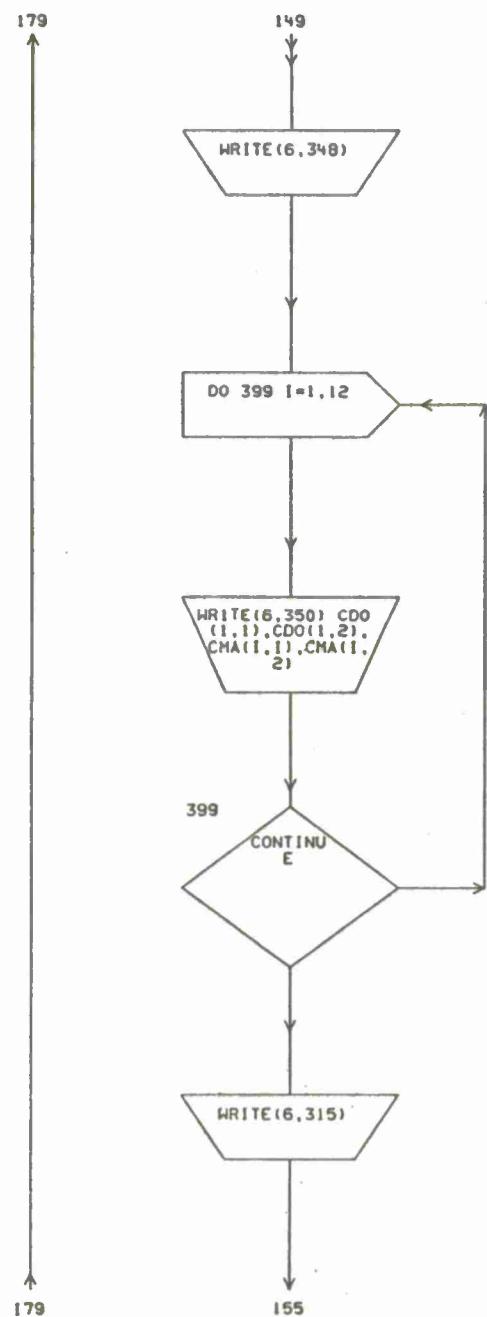


NWC TP 5864

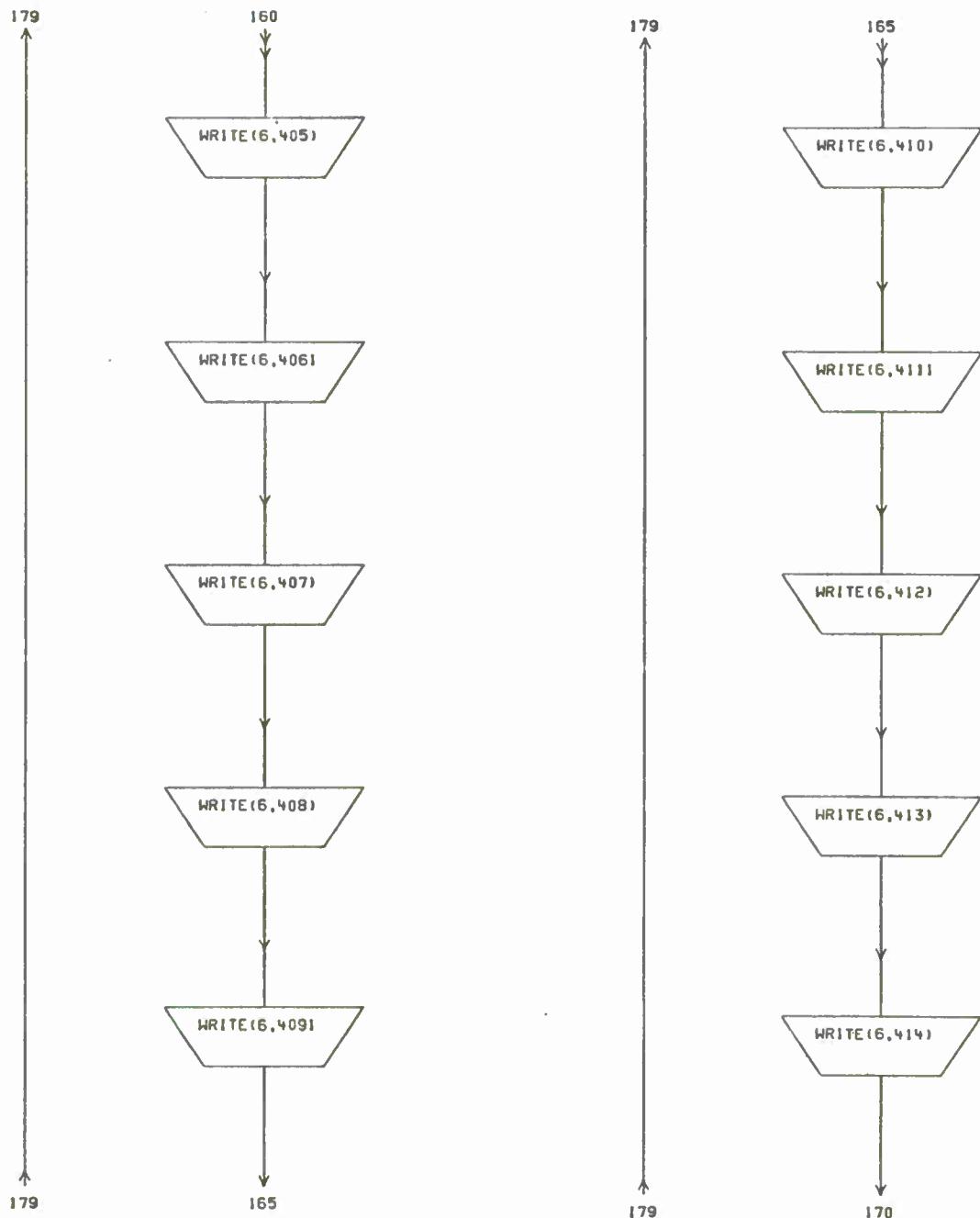


NWC TP 5864

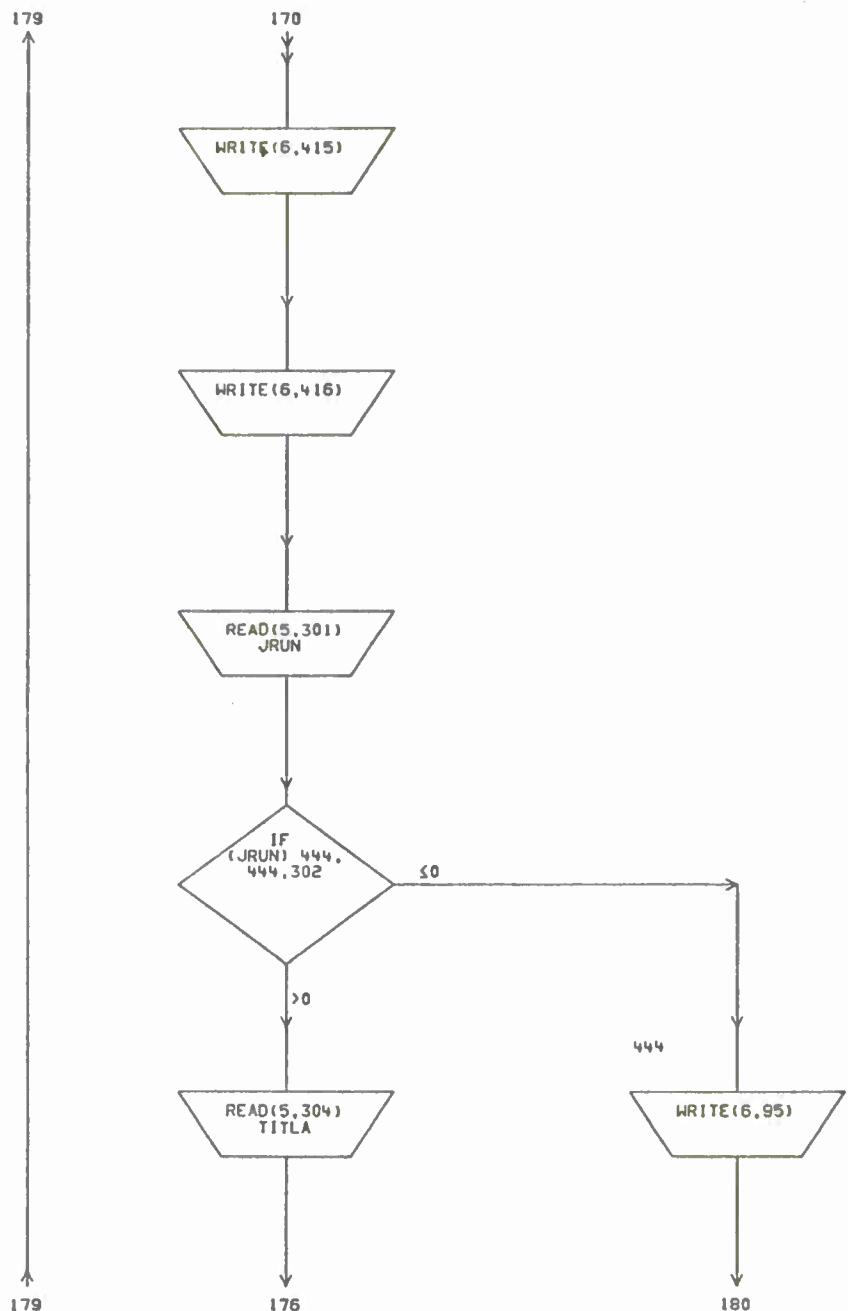


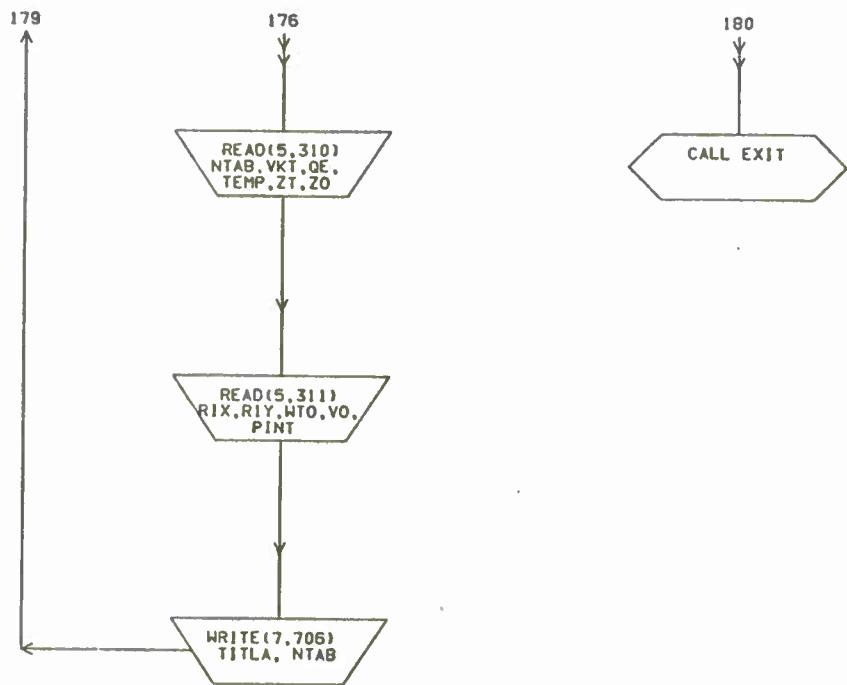


NWC TP 5864



NWC TP 5864





Appendix E
TYPICAL TRAJECTORY TABLE OUTPUT

This represents a typical trajectory table for the 20-mm M56 projectile, fired at +15 degrees elevation.

NWC TP 5864

TRAJECTORY TABLE NUMBER 1

ALTITUDE: .0 FEET GE: 15.0 DEGREES

VELOCITY: .0 KTAS TEMP: 59.0 DEG F

TIME THETA	X Z	DIST DRAG	V YAW	DH MACH	CMA SPIN	ENG SG
.00	0.	0.	3360.0	.0	1.89	39099.
15.00	0.	17.831	.0048	3.01	2016.	3.87
.10	313.	324.	3121.5	.2	1.95	33746.
14.95	84.	15.782	.0057	2.80	1980.	4.20
.20	604.	626.	2909.5	.6	2.01	29318.
14.89	161.	14.023	.0068	2.61	1946.	4.55
.30	877.	907.	2720.4	1.4	2.07	25631.
14.82	234.	12.565	.0080	2.44	1915.	4.91
.40	1131.	1171.	2550.3	2.4	2.14	22526.
14.76	301.	11.379	.0092	2.29	1889.	5.25
.50	1371.	1418.	2395.9	3.6	2.21	19880.
14.68	364.	10.358	.0107	2.15	1863.	5.62
.60	1596.	1651.	2254.9	5.1	2.27	17610.
14.61	422.	9.429	.0123	2.02	1839.	5.02
.70	1808.	1870.	2126.2	6.8	2.34	15657.
14.52	477.	8.578	.0141	1.91	1817.	5.44
.80	2008.	2076.	2008.9	8.8	2.40	13976.
14.44	529.	7.812	.0162	1.80	1796.	6.88
.90	2197.	2272.	1901.7	10.9	2.46	12524.
14.35	578.	7.126	.0184	1.71	1777.	7.36
1.00	2377.	2457.	1803.6	13.3	2.51	11266.
14.25	624.	6.524	.0210	1.62	1759.	7.85
1.10	2547.	2633.	1713.6	15.8	2.56	10169.
14.15	667.	5.983	.0238	1.54	1743.	8.36

TRAJECTORY TABLE NUMBER 1 (CON'T)

ALTITUDE: .0 FEET QE: 15.0 DEGREES

VELOCITY: .0 KTAS TEMP: 59.0 DEG F

TIME	X	DIST	V	DH	CMA	ENG
THETA	Z	DRAG	YAW	MACH	SPIN	SG
1.20	2709.	2800.	1630.8	18.5	2.62	9211.
14.04	707.	5.501	.0268	1.47	1727.	8.89
1.30	2864.	2959.	1554.5	21.5	2.68	8369.
13.93	746.	5.070	.0300	1.40	1712.	9.41
1.40	3011.	3111.	1484.0	24.6	2.73	7527.
13.81	782.	4.681	.0336	1.33	1698.	9.97
1.50	3152.	3256.	1418.8	27.8	2.78	6972.
13.69	817.	4.329	.0375	1.28	1685.	10.56
1.60	3287.	3395.	1358.3	31.3	2.83	6390.
13.56	850.	4.010	.0418	1.22	1673.	11.17
1.70	3417.	3528.	1302.2	34.9	2.89	5873.
13.43	881.	3.682	.0463	1.17	1661.	11.76
1.80	3541.	3655.	1250.5	38.7	2.95	5416.
13.28	910.	3.367	.0509	1.12	1650.	12.34
1.90	3660.	3779.	1203.1	42.7	3.00	5013.
13.14	938.	2.911	.0559	1.08	1640.	12.94
2.00	3775.	3897.	1161.8	46.8	3.05	4575.
12.99	965.	2.533	.0608	1.04	1630.	13.50
2.10	3887.	4011.	1125.7	51.1	3.09	4388.
12.83	990.	2.228	.0657	1.01	1621.	14.04
2.20	3995.	4122.	1093.7	55.6	3.15	4143.
12.67	1015.	1.910	.0700	.98	1612.	14.45
2.30	4101.	4230.	1066.2	60.3	3.18	3937.
12.50	1038.	1.615	.0747	.96	1604.	14.97

TRAJECTORY TABLE NUMBER 1 (CON'T)

ALTITUDE: .0 FEET QE: 15.0 DEGREES

VELOCITY: .0 KTAS TEMP: 59.0 DEG F

TIME THETA	X Z	DIST DRAG	V YAW	DH MACH	CMA SPIN	ENG SG
2.40 12.33	4204. 1061.	4335. 1.381	1042.7 .0803	55.3 .94	3.15 1597.	3755. 15.65
2.50 12.16	4304. 1083.	4439. 1.193	1022.4 .0855	70.4 .92	3.13 1590.	3521. 16.26
2.60 11.98	4404. 1104.	4540. 1.039	1004.8 .0904	75.8 .90	3.11 1583.	3497. 16.81
2.70 11.80	4501. 1125.	4640. .962	989.4 .0951	81.4 .89	3.09 1576.	3390. 17.30
2.80 11.61	4597. 1145.	4738. .912	975.1 .0995	87.2 .88	3.07 1569.	3293. 17.77
2.90 11.43	4692. 1164.	4834. .865	961.4 .1040	93.3 .87	3.05 1563.	3201. 18.23
3.00 11.24	4786. 1183.	4930. .823	948.5 .1086	99.6 .85	3.04 1557.	3116. 18.69
3.10 11.05	4878. 1201.	5024. .783	936.1 .1132	106.2 .84	3.03 1551.	3035. 19.13
3.20 10.85	4970. 1219.	5117. .747	924.4 .1178	113.0 .83	3.01 1544.	2959. 19.57
3.30 10.65	5060. 1236.	5209. .713	913.1 .1224	120.1 .82	3.00 1539.	2888. 20.00
3.40 10.45	5149. 1252.	5299. .682	902.3 .1270	127.3 .81	2.99 1533.	2820. 20.42
3.50 10.25	5237. 1268.	5389. .653	892.0 .1317	134.9 .80	2.97 1527.	2756. 20.83

NWC TP 5864

TRAJECTORY TABLE NUMBER 1 (CON'T)

ALTITUDE: .0 FEET QE: 15.0 DEGREES

VELOCITY: .0 KTAS TEMP: 59.0 DEG F

TIME THETA	X Z	DIST DRAG	V YAW	DH MACH	CMA SPIN	ENG SG
3.60	5325.	5477.	882.1	142.6	2.97	2695.
10.05	1284.	.634	.1360	.79	1521.	21.18
3.70	5411.	5565.	872.5	150.6	2.97	2637.
9.84	1299.	.620	.1402	.79	1516.	21.51
3.80	5497.	5652.	863.1	158.9	2.97	2580.
9.63	1314.	.606	.1444	.78	1510.	21.83
3.90	5581.	5737.	853.9	167.4	2.97	2525.
9.42	1328.	.593	.1488	.77	1505.	22.15
4.00	5665.	5822.	844.9	176.1	2.97	2473.
9.21	1342.	.580	.1532	.76	1500.	22.48
4.10	5748.	5906.	836.1	185.0	2.97	2421.
8.99	1355.	.568	.1577	.75	1494.	22.80
4.20	5830.	5989.	827.5	194.2	2.97	2372.
8.77	1368.	.556	.1623	.75	1489.	23.13
4.30	5912.	6071.	819.1	203.6	2.97	2323.
8.55	1380.	.545	.1669	.74	1484.	23.45
4.40	5992.	6152.	810.8	213.3	2.97	2277.
8.32	1392.	.534	.1717	.73	1479.	23.78
4.50	6072.	6232.	802.7	223.1	2.97	2232.
8.10	1404.	.523	.1765	.72	1474.	24.11
4.60	6151.	6312.	794.8	233.2	2.97	2188.
7.87	1415.	.512	.1814	.72	1469.	24.44
4.70	6230.	6391.	787.0	243.6	2.97	2145.
7.64	1426.	.502	.1864	.71	1464.	24.77

TRAJECTORY TABLE NUMBER 1 (CON'T)

TIME	ALTITUDE:	.0 FEET	QE:	15.0 DEGREES			
	VELOCITY:	.0 KTAS	TEMP:	59.0 DEG F			
TIME	X THETA	Z	DIST DRAG	V YAW	DH MACH	CMA SPIN	ENG SG
4.80	6307.	6469.	779.4	254.1	2.97	2104.	
7.41	1436.	.492	.1914	.70	1460.	25.10	
4.90	6334.	5546.	772.0	254.9	2.97	2064.	
7.17	1446.	.433	.1965	.70	1455.	25.43	
5.00	6460.	6622.	764.7	275.9	2.97	2025.	
6.93	1455.	.474	.2018	.69	1450.	25.76	
5.10	6536.	6698.	757.5	287.1	2.97	1987.	
6.69	1464.	.455	.2070	.58	1446.	25.10	
5.20	6611.	6773.	750.5	298.6	2.97	1951.	
6.45	1473.	.456	.2124	.58	1441.	26.43	
5.30	6685.	6847.	743.6	310.2	2.97	1915.	
5.20	1481.	.448	.2178	.57	1437.	25.75	
5.40	6759.	6921.	736.9	322.1	2.97	1880.	
5.96	1489.	.439	.2234	.66	1432.	27.09	
5.50	6832.	6994.	730.2	334.2	2.97	1847.	
5.71	1496.	.431	.2239	.56	1428.	27.43	
5.60	6904.	7066.	723.7	346.5	2.97	1814.	
5.45	1503.	.424	.2346	.65	1424.	27.75	
5.70	6976.	7137.	717.4	359.1	2.97	1782.	
5.20	1510.	.416	.2404	.55	1420.	28.09	
5.80	7047.	7208.	711.1	371.8	2.97	1751.	
4.94	1516.	.409	.2462	.54	1415.	28.43	
5.90	7118.	7279.	705.0	384.8	2.97	1721.	
4.58	1522.	.402	.2520	.54	1411.	28.76	

TRAJECTORY TABLE NUMBER 1 (CON'T)

ALTITUDE: .0 FEET QE: 15.0 DEGREES

VELOCITY: .0 KTAS TEMP: 59.0 DEG F

TIME THETA	X Z	DIST DRAG	V YAW	DH MACH	CMA SPIN	ENG SG
6.00	7188.	7348.	699.0	397.9	2.97	1692.
4.42	1528.	.395	.2580	.63	1407.	29.09
6.10	7257.	7417.	693.1	411.3	2.97	1564.
4.16	1533.	.388	.2640	.62	1403.	29.43
6.20	7326.	7486.	687.3	424.9	2.97	1536.
3.89	1538.	.382	.2701	.62	1399.	29.76
6.30	7394.	7553.	681.6	438.8	2.97	1509.
3.62	1542.	.375	.2763	.61	1395.	30.09
6.40	7462.	7620.	676.0	452.8	2.97	1583.
3.35	1547.	.369	.2825	.61	1391.	30.42
6.50	7529.	7687.	670.6	467.0	2.97	1557.
3.08	1550.	.363	.2888	.60	1387.	30.75
6.60	7596.	7753.	665.2	481.5	2.97	1532.
2.80	1554.	.357	.2951	.60	1384.	31.08
6.70	7662.	7919.	659.9	496.1	2.97	1508.
2.52	1557.	.352	.3015	.59	1380.	31.41
6.80	7728.	7883.	654.7	511.0	2.97	1485.
2.24	1560.	.346	.3080	.59	1376.	31.74
6.90	7793.	7948.	649.6	526.1	2.97	1462.
1.96	1562.	.341	.3145	.59	1372.	32.07
7.00	7858.	8012.	644.6	541.3	2.97	1439.
1.68	1564.	.336	.3211	.58	1369.	32.40
7.10	7922.	8075.	639.7	556.8	2.97	1417.
1.39	1566.	.331	.3277	.58	1365.	32.73

TRAJECTORY TABLE NUMBER 1 (CON'T)

ALTITUDE: .0 FEET QE: 15.0 DEGREES

VELOCITY: .0 KTAS TEMP: 59.0 DEG F

TIME THETA	X Z	DIST DRAG	V YAW	DH MACH	CMA SPIN	ENG SG
7.20	7985.	8138.	634.9	572.5	2.97	1396.
1.10	1567.	.326	.3344	.57	1362.	33.05
7.30	8049.	8200.	630.2	588.4	2.97	1375.
.81	1568.	.321	.3412	.57	1358.	33.38
7.40	8111.	8262.	625.6	604.5	2.97	1355.
.52	1569.	.316	.3479	.56	1354.	33.70
7.50	8174.	8323.	621.0	620.8	2.97	1336.
.22	1569.	.311	.3548	.56	1351.	34.02
7.60	8236.	8384.	616.5	637.3	2.97	1315.
-.08	1569.	.307	.3616	.56	1348.	34.34
7.70	8297.	8444.	612.1	654.0	2.97	1298.
-.38	1569.	.303	.3685	.55	1344.	34.66
7.80	8358.	8504.	607.8	670.9	2.97	1279.
-.68	1569.	.298	.3755	.55	1341.	34.98
7.90	8419.	8563.	603.6	688.0	2.97	1262.
-.98	1568.	.294	.3824	.54	1337.	35.30
8.00	8479.	8622.	599.4	705.3	2.97	1244.
-1.29	1567.	.290	.3894	.54	1334.	35.61
8.10	8539.	8681.	595.3	722.8	2.97	1227.
-1.60	1565.	.286	.3965	.54	1331.	35.92
8.20	8598.	8739.	591.3	740.5	2.97	1211.
-1.91	1563.	.283	.4035	.53	1328.	36.23
8.30	8657.	8796.	587.4	758.5	2.97	1195.
-2.22	1561.	.279	.4106	.53	1324.	36.54

TRAJECTORY TABLE NUMBER 1 (CON'T)

ALTITUDE: .0 FEET QE: 15.0 DEGREES
 VELOCITY: .0 KTAS TEMP: 59.0 DEG F

TIME THETA	X Z	DIST DRAG	V YAW	DH MACH	CMA SPIN	ENG SG
8.40 -2.54	8715. 1559.	8853. .275	583.5 .4177	776.6 .53	2.97 1321.	1179. 36.85
8.50 -2.85	8773. 1556.	8910. .272	579.7 .4248	794.9 .52	2.97 1318.	1164. 37.15
8.60 -3.17	8831. 1553.	8966. .268	575.9 .4320	813.4 .52	2.97 1315.	1149. 37.45
8.70 -3.49	8888. 1550.	9022. .265	572.3 .4391	832.0 .52	2.97 1312.	1134. 37.75
8.80 -3.82	8945. 1546.	9078. .262	568.7 .4462	850.9 .51	2.97 1309.	1120. 38.05
8.90 -4.14	9002. 1542.	9133. .258	565.1 .4534	870.0 .51	2.97 1306.	1106. 38.34
9.00 -4.47	9058. 1538.	9188. .255	561.7 .4605	889.3 .51	2.97 1303.	1093. 38.63
9.10 -4.79	9114. 1533.	9242. .252	558.2 .4676	908.8 .50	2.97 1300.	1079. 38.92
9.20 -5.12	9169. 1528.	9296. .249	554.9 .4748	928.4 .50	2.97 1297.	1066. 39.21
9.30 -5.46	9224. 1523.	9349. .246	551.6 .4819	948.3 .50	2.97 1294.	1054. 39.49
9.40 -5.79	9279. 1518.	9402. .244	548.4 .4890	968.4 .49	2.97 1291.	1041. 39.77
9.50 -6.12	9333. 1512.	9455. .241	545.2 .4960	988.6 .49	2.97 1288.	1029. 40.04

TRAJECTORY TABLE NUMBER 1 (CONT)

ALTITUDE: .0 FEET QE: 15.0 DEGREES

VELOCITY: .0 KTAS TEMP: 59.0 DEG F

TIME THETA	X Z	DIST DRAG	V YAW	DH MACH	CMA SPIN	ENG SG
9.60	9387.	9508.	542.1	1009.0	2.97	1018.
-6.46	1506.	.238	.5031	.49	1285.	40.32
9.70	9441.	9560.	539.0	1029.7	2.97	1006.
-6.50	1500.	.235	.5101	.49	1282.	40.59
9.80	9495.	9611.	536.0	1050.5	2.97	995.
-7.14	1494.	.233	.5171	.48	1279.	40.85
9.90	9548.	9663.	533.1	1071.5	2.97	984.
-7.48	1487.	.230	.5240	.48	1277.	41.11
10.00	9600.	9714.	530.2	1092.7	2.97	974.
-7.83	1480.	.228	.5309	.48	1274.	41.37
10.10	9653.	9764.	527.4	1114.1	2.97	963.
-8.17	1472.	.226	.5378	.48	1271.	41.63
10.20	9705.	9815.	524.6	1135.7	2.97	953.
-8.52	1465.	.223	.5446	.47	1268.	41.88
10.30	9756.	9865.	521.9	1157.4	2.97	943.
-8.87	1457.	.221	.5513	.47	1266.	42.13
10.40	9808.	9914.	519.2	1179.4	2.97	934.
-9.22	1449.	.219	.5580	.47	1263.	42.37
10.50	9859.	9963.	516.5	1201.5	2.97	924.
-9.57	1440.	.217	.5646	.47	1260.	42.61
10.60	9910.	10012.	514.0	1223.9	2.97	915.
-9.92	1431.	.215	.5712	.46	1258.	42.84
10.70	9960.	10061.	511.4	1246.4	2.97	906.
-10.27	1422.	.213	.5777	.46	1255.	43.07

TRAJECTORY TABLE NUMBER 1 (CON'T)

ALTITUDE: .0 FEET QE: 15.0 DEGREES

VELOCITY: .0 KTAS TEMP: 59.0 DEG F

TIME THETA	X Z	DIST DRAG	V YAW	DH MACH	CMA SPIN	ENG SG
10.80	10010.	10110.	509.0	1269.1	2.97	897.
-10.63	1413.	.211	.5841	.46	1252.	43.30
10.90	10060.	10158.	506.5	1292.0	2.97	889.
-10.99	1454.	.209	.5905	.46	1250.	43.52
11.00	10110.	10205.	504.1	1315.0	2.97	880.
-11.34	1394.	.207	.5967	.45	1247.	43.74
11.10	10159.	10253.	501.8	1338.3	2.97	872.
-11.70	1384.	.205	.6029	.45	1244.	43.95
11.20	10208.	10300.	499.5	1361.7	2.97	864.
-12.06	1374.	.203	.6089	.45	1242.	44.15
11.30	10257.	10347.	497.3	1385.3	2.97	856.
-12.42	1363.	.201	.6149	.45	1239.	44.36
11.40	10305.	10393.	495.1	1409.1	2.97	849.
-12.79	1352.	.200	.6208	.45	1237.	44.55
11.50	10353.	10440.	492.9	1433.1	2.97	841.
-13.15	1341.	.198	.6266	.44	1234.	44.75
11.60	10401.	10486.	490.8	1457.3	2.97	834.
-13.51	1330.	.196	.6322	.44	1232.	44.93
11.70	10449.	10532.	488.7	1481.6	2.97	827.
-13.88	1318.	.195	.6378	.44	1229.	45.12
11.80	10496.	10577.	486.7	1506.2	2.97	820.
-14.25	1306.	.193	.6432	.44	1227.	45.29
11.90	10543.	10622.	484.7	1530.9	2.97	814.
-14.61	1294.	.192	.6486	.44	1224.	45.47

TRAJECTORY TABLE NUMBER 1 (CONT)

ALTITUDE: .0 FEET QE: 15.0 DEGREES

VELOCITY: .0 KTAS TEMP: 59.0 DEG F

TIME THETA	X Z	DIST DRAG	V YAW	DH MACH	CMA SPIN	ENG SG
12.00	10590.	10667.	482.7	1555.8	2.97	807.
-14.98	1282.	.190	.6538	.43	1222.	45.63
12.10	10636.	10712.	480.8	1580.8	2.97	801.
-15.35	1269.	.189	.6588	.43	1219.	45.79
12.20	10683.	10756.	479.0	1606.1	2.97	795.
-15.72	1256.	.188	.6638	.43	1217.	45.95
12.30	10729.	10800.	477.1	1631.5	2.97	788.
-16.09	1243.	.186	.6686	.43	1215.	45.10
12.40	10774.	10844.	475.4	1657.1	2.97	783.
-16.46	1230.	.185	.6733	.43	1212.	46.25
12.50	10820.	10888.	473.6	1682.9	2.97	777.
-16.84	1216.	.184	.6778	.43	1210.	46.38
12.60	10865.	10931.	471.9	1708.8	2.97	771.
-17.21	1202.	.182	.6822	.42	1208.	46.52
12.70	10910.	10974.	470.2	1734.9	2.97	766.
-17.58	1188.	.181	.6865	.42	1205.	46.65
12.80	10955.	11017.	468.6	1761.2	2.97	760.
-17.96	1174.	.180	.6906	.42	1203.	46.77
12.90	10999.	11060.	467.0	1787.7	2.97	755.
-18.33	1159.	.179	.6945	.42	1200.	46.89
13.00	11043.	11102.	465.4	1814.4	2.97	750.
-18.71	1145.	.178	.6983	.42	1198.	47.00
13.10	11087.	11145.	463.9	1841.2	2.97	745.
-19.08	1130.	.177	.7020	.42	1196.	47.10

TRAJECTORY TABLE NUMBER 1 (CON'T)

ALTITUDE: .0 FEET QE: 15.0 DEGREES
 VELOCITY: .0 KTAS TEMP: 59.0 DEG F

TIME THETA	X Z	DIST DRAG	V YAW	DH MACH	CMA SPIN	ENG SG
13.20 -19.46	11131. 1114.	11187. .176	462.4 .7055	1868.2 .42	2.97 1194.	740. 47.20
13.30 -19.83	11174. 1099.	11228. .175	460.9 .7088	1895.4 .41	2.97 1191.	736. 47.30
13.40 -20.21	11218. 1083.	11270. .174	459.5 .7120	1922.7 .41	2.97 1189.	731. 47.38
13.50 -20.59	11261. 1067.	11311. .173	458.1 .7150	1950.2 .41	2.97 1187.	727. 47.47
13.60 -20.96	11303. 1051.	11352. .172	456.8 .7179	1977.9 .41	2.97 1184.	723. 47.54
13.70 -21.34	11346. 1034.	11393. .171	455.4 .7205	2005.8 .41	2.97 1182.	718. 47.61
13.80 -21.72	11388. 1018.	11434. .170	454.2 .7231	2033.8 .41	2.97 1180.	714. 47.68
13.90 -22.09	11430. 1001.	11474. .169	452.9 .7254	2062.0 .41	2.97 1178.	710. 47.74
14.00 -22.47	11472. 984.	11514. .168	451.7 .7276	2090.4 .41	2.97 1176.	707. 47.79
14.10 -22.85	11514. 966.	11554. .168	450.5 .7296	2118.9 .41	2.97 1173.	703. 47.84
14.20 -23.22	11555. 949.	11594. .167	449.7 .7315	2147.6 .40	2.97 1171.	699. 47.88
14.30 -23.60	11596. 931.	11634. .166	448.2 .7332	2176.4 .40	2.97 1169.	696. 47.91

TRAJECTORY TABLE NUMBER 1 (CON'T)

ALTITUDE: .0 FEET GE: 15.0 DEGREES

VELOCITY: .0 KTAS TEMP: 59.0 DEG F

TIME THETA	X Z	DIST DRAG	V YAW	DH MACH	CMA SPIN	ENG SG
14.40 -23.98	11637. 913.	11673. .165	447.1 .7347	2205.5 .40	2.97 1167.	692. 47.94
14.50 -24.36	11578. 894.	11712. .165	446.0 .7360	2234.7 .40	2.97 1165.	689. 47.97
14.60 -24.73	11719. 876.	11751. .164	444.9 .7372	2264.0 .40	2.97 1162.	686. 47.99
14.70 -25.11	11759. 857.	11790. .163	443.9 .7382	2293.6 .40	2.97 1160.	683. 48.00
14.80 -25.48	11799. 838.	11829. .163	442.9 .7390	2323.3 .40	2.97 1158.	679. 48.01
14.90 -25.86	11839. 819.	11867. .162	442.0 .7397	2353.1 .40	2.97 1156.	677. 48.01
15.00 -26.23	11879. 800.	11905. .162	441.0 .7402	2383.1 .40	2.97 1154.	674. 48.00
15.10 -26.61	11918. 780.	11944. .161	440.1 .7405	2413.3 .40	2.97 1152.	671. 47.99
15.20 -26.98	11957. 760.	11981. .160	439.3 .7407	2443.6 .39	2.97 1150.	668. 47.98
15.30 -27.36	11996. 740.	12019. .160	438.4 .7407	2474.1 .39	2.97 1148.	666. 47.96
15.40 -27.73	12035. 720.	12057. .159	437.6 .7405	2504.8 .39	2.97 1145.	663. 47.93
15.50 -28.10	12074. 700.	12094. .159	436.8 .7402	2535.6 .39	2.97 1143.	661. 47.90

TRAJECTORY TABLE NUMBER 1 (CONT)

ALTITUDE: .0 FEET QE: 15.0 DEGREES
 VELOCITY: .0 KTAS TEMP: 59.0 DEG F

TIME THETA	X Z	DIST DRAG	V YAW	DH MACH	CMA SPIN	ENG SG
15.60 -28.47	12112. 679.	12131. .159	436.0 .7397	2555.6 .39	2.97 1141.	558. 47.86
15.70 -28.85	12150. 658.	12168. .158	435.3 .7391	2597.7 .39	2.97 1139.	656. 47.82
15.80 -29.22	12188. 637.	12205. .158	434.5 .7383	2629.0 .39	2.97 1137.	654. 47.77
15.90 -29.59	12226. 616.	12242. .157	433.8 .7373	2660.5 .30	2.97 1135.	652. 47.72
16.00 -29.95	12264. 594.	12278. .157	433.1 .7362	2692.1 .39	2.97 1133.	650. 47.66
16.10 -30.32	12301. 572.	12315. .157	432.5 .7350	2723.8 .39	2.97 1131.	648. 47.60
16.20 -30.69	12339. 550.	12351. .156	431.9 .7336	2755.8 .39	2.97 1129.	646. 47.53
16.30 -31.05	12376. 528.	12387. .156	431.3 .7320	2787.8 .39	2.97 1127.	644. 47.46
16.40 -31.42	12412. 506.	12423. .156	430.7 .7303	2820.1 .39	2.97 1125.	642. 47.39
16.50 -31.79	12449. 483.	12458. .155	430.1 .7285	2852.4 .39	2.97 1123.	641. 47.30
16.60 -32.15	12486. 461.	12494. .155	429.6 .7265	2885.0 .39	2.97 1121.	639. 47.22
16.70 -32.51	12522. 438.	12529. .155	429.0 .7244	2917.6 .39	2.97 1119.	637. 47.13

TRAJECTORY TABLE NUMBER 1 (CON'T)

ALTITUDE: .0 FEET QE: 15.0 DEGREES

VELOCITY: .0 KTAS TEMP: 59.0 DEG F

TIME	X	DIST	V	DH	CMA	ENG
THETA	Z	DRAG	YAW	MACH	SPIN	SG
16.80	12558.	12555.	428.5	2950.5	2.97	636.
-32.88	414.	.154	.7222	.38	1117.	47.03
16.90	12594.	12600.	428.1	2983.5	2.97	635.
-33.24	391.	.154	.7198	.38	1115.	46.93
17.00	12630.	12635.	427.6	3016.6	2.97	633.
-33.60	367.	.154	.7173	.38	1113.	46.83
17.10	12665.	12670.	427.2	3049.9	2.97	632.
-33.95	344.	.154	.7147	.38	1111.	46.72
17.20	12700.	12704.	426.7	3083.3	2.97	631.
-34.31	320.	.154	.7119	.38	1109.	46.60
17.30	12736.	12739.	426.3	3116.9	2.97	629.
-34.67	296.	.153	.7090	.38	1107.	46.49
17.40	12771.	12773.	425.9	3150.6	2.97	628.
-35.02	271.	.153	.7061	.38	1105.	46.37
17.50	12805.	12808.	425.6	3184.4	2.97	627.
-35.38	247.	.153	.7030	.38	1103.	46.24
17.60	12840.	12842.	425.2	3218.5	2.97	626.
-35.73	222.	.153	.6998	.38	1101.	46.11
17.70	12874.	12876.	424.9	3252.6	2.97	625.
-36.08	197.	.153	.6965	.38	1099.	45.98
17.80	12909.	12910.	424.6	3286.9	2.97	624.
-36.43	172.	.153	.6931	.38	1097.	45.85
17.90	12943.	12944.	424.3	3321.3	2.97	624.
-36.78	147.	.153	.6896	.38	1095.	45.71

TRAJECTORY TABLE NUMBER 1 (CON'T)

ALTITUDE: .0 FEET QE: 15.0 DEGREES

VELOCITY: .0 KTAS TEMP: 59.0 DEG F

TIME THETA	X Z	DIST DRAG	V YAW	DH MACH	CMA SPIN	ENG SG
18.00 -37.13	12977. 121.	12977. .153	424.0 .5860	3355.9 .38	2.97 1093.	523. 45.56
18.10 -37.47	13010. 95.	13011. .152	423.8 .5823	3390.7 .38	2.97 1091.	622. 45.42
18.20 -37.82	13044. 70.	13044. .152	423.5 .6785	3425.5 .38	2.97 1089.	621. 45.27
18.30 -38.16	13077. 44.	13077. .152	423.3 .6746	3460.5 .38	2.97 1087.	621. 45.11
18.40 -38.50	13110. 17.	13110. .152	423.1 .6707	3495.7 .38	2.97 1085.	520. 44.96
TIME, SEC 18.47	RANGE, FT 13132.0	VEL, FPS 422.9	THETA -38.8	SPIN 1083.	SG 44.96	

NWC TP 5864

TRAJECTORY TABLE NUMBER 1 (CON'T)

BALLISTIC DATA

PROJECTILE DIAMETER	20.00 MILLIMETER
PROJECTILE LENGTH	3.8 CALIBERS
PROJECTILE WEIGHT	.2228570 POUNDS
	1560.00 GRAINS
	101.09 GRAMS
AXIAL MOMENT OF INERTIA	.0187466 POUND-INCH SQ.
TRANSVERSE MOMENT OF INERTIA	.1397623 POUND-INCH SQ.
AXIAL RADIUS OF GYRATION	.3683433 CALIBERS
TRANSVERSE RADIUS OF GYRATION	1.0057418 CALIBERS
CENTER OF GRAVITY, FROM BASE	1.513 INCHES
MUZZLE VELOCITY	3360.0 FEET/SECOND
BARREL TWIST	25.40050 CALIBERS/TURN
RIFLING EXIT ANGLE	7 DEGREES 3 MINUTES
YAW-DRAG COEFFICIENT, PER RADIAN SQUARED	5.8
ROLL DAMPING MOMENT COEFFICIENT, PER RAD/SEC	-.0100

TRAJECTORY TABLE NUMBER 1 (CON'T)

ALTITUDE: .0 FEET QE: 15.0 DEGREES
VELOCITY: .0 KTAS TEMP: 59.0 DEG F

DRAG COEFFICIENT AND STATIC MOMENT COEFFICIENT TABLE

MACH	CDO	MACH	CMA
.80	.211	.80	2.970
.90	.258	.90	3.100
1.00	.440	.97	3.190
1.12	.551	1.00	3.110
1.20	.558	1.20	2.850
1.50	.522	1.50	2.590
1.70	.500	1.70	2.460
2.00	.470	1.99	2.290
2.30	.438	2.25	2.160
2.50	.420	2.50	2.040
3.00	.393	3.00	1.890
3.60	.383	3.60	1.830

LEGEND

TIME	TIME OF FLIGHT, SECONDS
X	HORIZONTAL RANGE, FEET
DIST	SLANT RANGE, FEET
V	VELOCITY, FEET/SECOND
DH	GRAVITY DROP, FEET
CMA	STATIC MOMENT COEFFICIENT
ENG	ENERGY, FOOT-POUNDS
THETA	IMPACT ANGLE, DEGREES
Z	ALTITUDE, FEET
DRAG	DRAG, POUNDS
YAW	YAW OF REPOSE, DEGREES
MACH	MACH NUMBER
SPIN	REVOLUTIONS/SECOND
SG	GYROSCOPIC STABILITY FACTOR
TEMP	SURFACE (MSL) TEMPERATURE
Q.E.	DIVE ANGLE, DEGREES

Appendix F
TYPICAL TRAJECTORY TABLE INPUT

This input deck was used to generate the trajectory table shown in Appendix E. (See Table 1 for definition of input parameters.)

JRUN
I2

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 80

RIX, RIV, WTO, VO, PINT
3F10.7, 2F10.2

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 80

NTAB, VKT, QE, TEMP, ZT, Z0
I2, 8X, 5F10.1

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 80

TITLE
5A6

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 80

CLP, DTM, DMM, CAL
4F10.5

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 80

FFD, FFM, CDD2, TWIST
5F10.5

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 80

KEA, KEB, CG
8X, I2, 8X, I2, F10.3

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 80

N, CDO(I,1), CDO(I,2), CMA(I,1), CMA(I,2)
I2, 8X, 4F10.4

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 80

1-12

FIGURE F-1. Input Data Deck, Parameters.

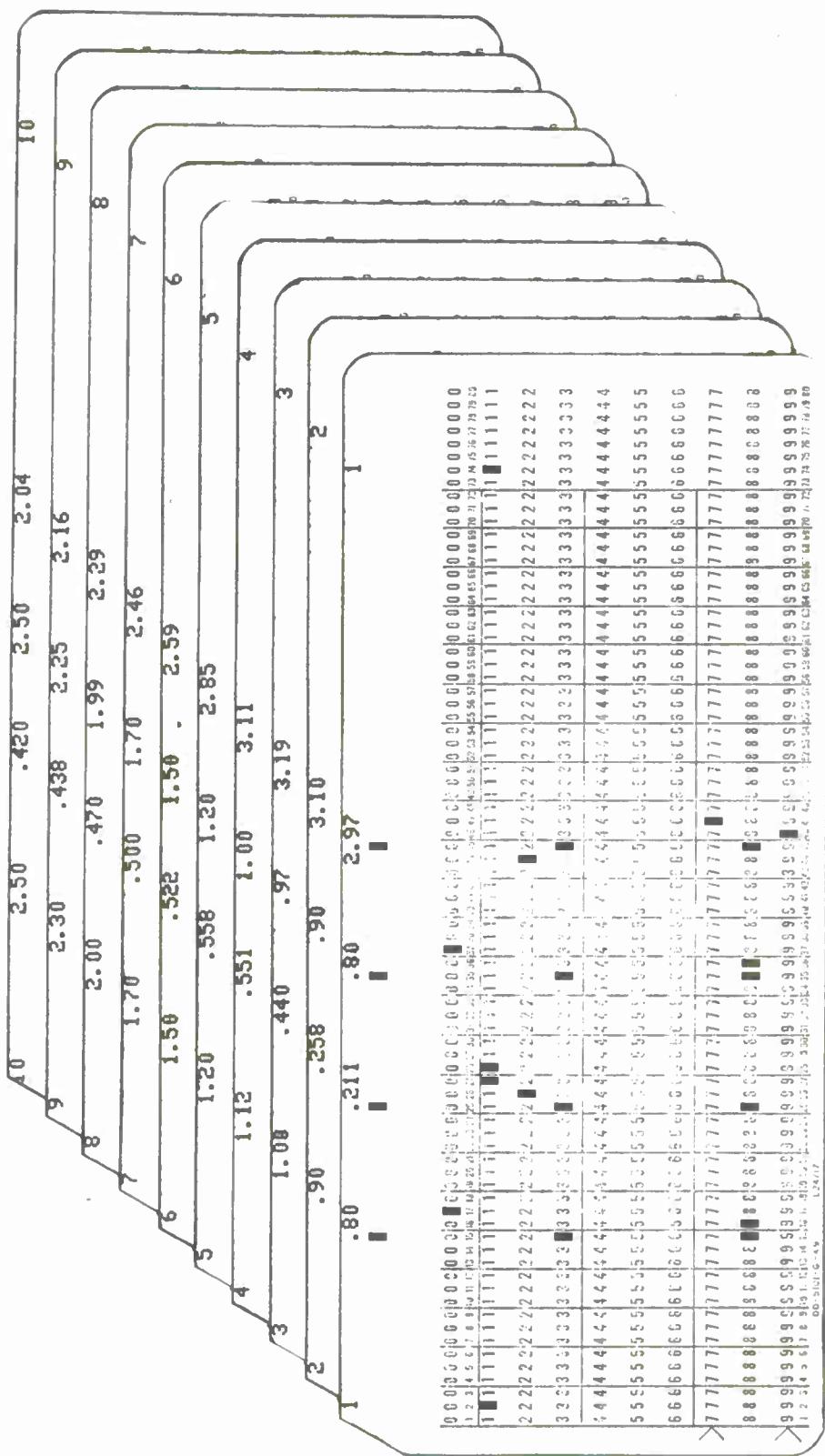


FIGURE F-2. Typical Input Data Deck, Cards 1 Through 19.

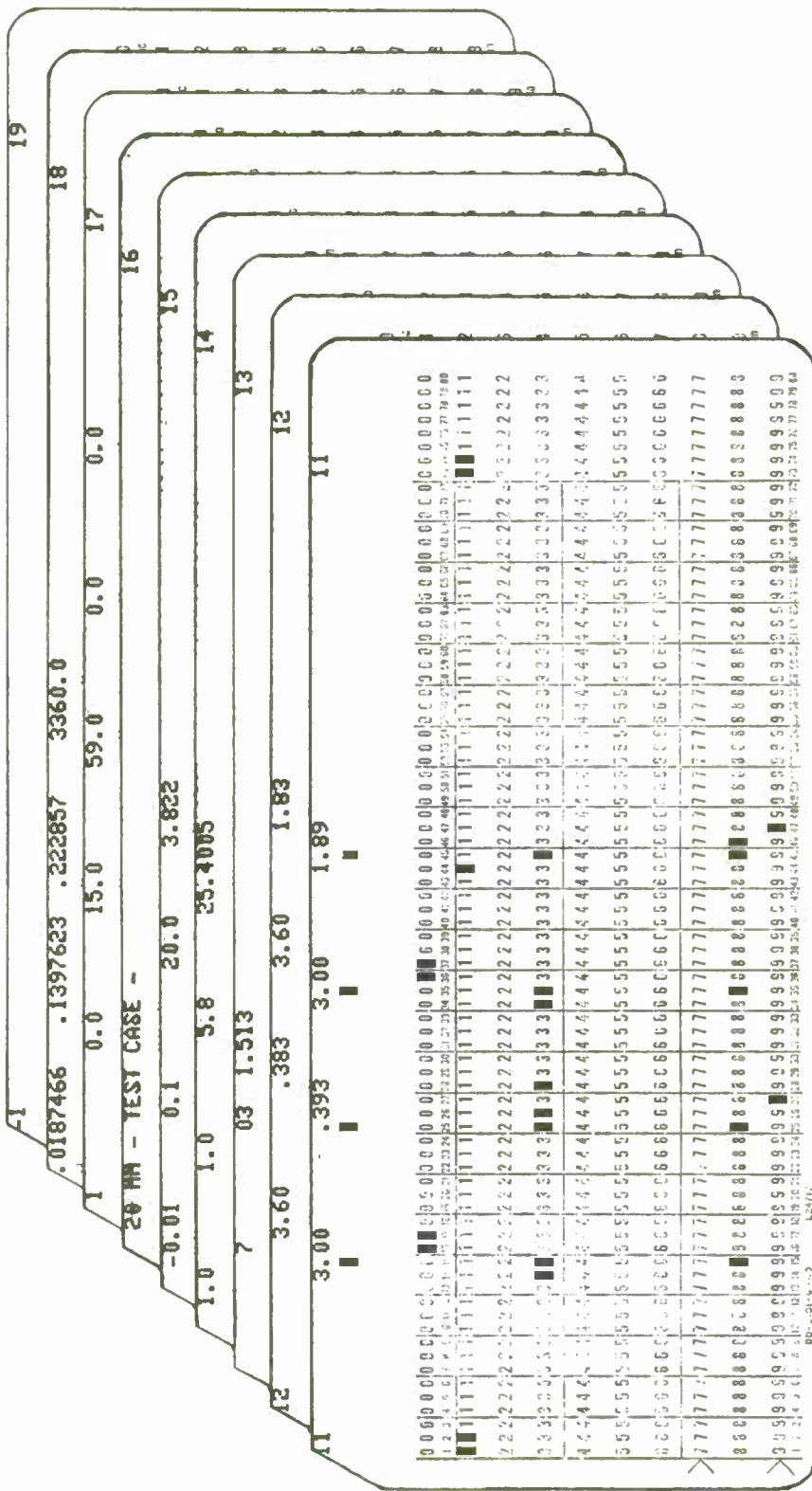


FIGURE F-2. (Contd.)

INITIAL DISTRIBUTION

3 Naval Air Systems Command

AIR-350 (1)

AIR-954 (2)

2 Naval Sea Systems Command

SEA-09G32

1 Naval Surface Weapons Center, Dahlgren Laboratory, Dahlgren (Attn: MIL)

1 Naval Surface Weapons Center, White Oak, Silver Spring, Md.

Technical Library (1)

1 Army Ballistic Research Laboratories, Aberdeen Proving Ground

Technical Library (1)

1 Frankford Arsenal (Technical Library)

1 Picatinny Arsenal (Technical Library)

1 Rock Island Arsenal (Technical Library)

1 Armament Development & Test Center, Eglin Air Force Base
(Technical Library)

2 Defense Documentation Center